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Data sheet for SINAMICS G120X

Article No. :

6SL3220-1YE36-0AF0



Figure similar

Client order no. :
Order no. :
Offer no. :
Remarks :

Rated data		
Input		
Number of phases	3 AC	
Line voltage	380 480 V +10 % -20 %	
Line frequency	47 63 Hz	
Rated voltage	400V IEC	480V NEC
Rated current (LO)	70.00 A	61.00 A
Rated current (HO)	62.00 A	54.00 A
Output		
Number of phases	3 AC	
Rated voltage	400V IEC	480V NEC ¹⁾
Rated power (LO)	37.00 kW	50.00 hp
Rated power (HO)	30.00 kW	40.00 hp
Rated current (LO)	75.00 A	65.00 A
Rated current (HO)	60.00 A	52.00 A
Rated current (IN)	77.00 A	
Max. output current	102.00 A	
Pulse frequency	4 kHz	
Output frequency for vector control	0 200 Hz	
Output frequency for V/f control	0 550 Hz	
Overland comphility		

Overload capability

Low Overload (LO)

110% base load current IL for 60 s in a 300 s cycle time

High Overload (HO)

150% x base load current IH for 60 s within a 600 s cycle time

General tech. specifications			
Power factor λ	0.90 0.95		
Offset factor $\cos \phi$	0.99		
Efficiency η	0.97		
Sound pressure level (1m)	70 dB		
Power loss ³⁾	1.110 kW		
Filter class (integrated)	RFI suppression filter for Category C2		
EMC category (with accessories)	Category C2		
Safety function "Safe Torque Off"	without SIRIUS device (e.g. via S7- 1500F)		
Communication			

Communication

PROFINET, EtherNet/IP

ltem no. : Consignment no. : Project :

Inputs /	Inputs / outputs			
Standard digital inputs				
Number	6			
Switching level: $0 \rightarrow 1$	11 V			
Switching level: $1 \rightarrow 0$	5 V			
Max. inrush current	15 mA			
Fail-safe digital inputs				
Number	1			
Digital outputs				
Number as relay changeover contact	2			
Output (resistive load)	DC 30 V, 5.0 A			
Number as transistor	0			
Analog / digital inputs				
Number	2 (Differential input)			
Resolution	10 bit			
Switching threshold as digital input				
0 → 1	4 V			
$1 \rightarrow 0$	1.6 V			
Analog outputs				
Number	1 (Non-isolated output)			
PTC/ KTY interface				
1 motor temperature sensor input, sensors that can be connected PTC, KTY and Thermo-Click, accuracy $\pm 5~^\circ\text{C}$				
Closed-loop co	ntrol techniques			

Closed-loop col	ittoi techniques
V/f linear / square-law / parameterizable	Yes
V/f with flux current control (FCC)	Yes
V/f ECO linear / square-law	Yes
Sensorless vector control	Yes
Vector control, with sensor	No
Encoderless torque control	No
Torque control, with encoder	No

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Ambient conditions			
Standard board coating type	Class 3C2, according to IEC 60721-3-3: 2002		
Cooling	Air cooling using an integrated fan		
Cooling air requirement	0.055 m ³ /s (1.942 ft ³ /s)		
Installation altitude	1,000 m (3,280.84 ft)		
Ambient temperature			
Operation	-20 45 °C (-4 113 °F)		
Transport	-40 70 °C (-40 158 °F)		
Storage	-25 55 °C (-13 131 °F)		
Relative humidity			
Max. operation	95 % At 40 °C (104 °F), condensation and icing not permissible		
Connections			
Signal cable			
Conductor cross-section	0.15 1.50 mm² (AWG 24 AWG 16)		
Line side			
Version	screw-type terminal		
Conductor cross-section	10.00 35.00 mm² (AWG 8 AWG 2)		
Motor end			
Version	Screw-type terminals		
Conductor cross-section	10.00 35.00 mm² (AWG 8 AWG 2)		
DC link (for braking resistor)			
PE connection	Screw-type terminals		
Max. motor cable length			

Ме	chanical data	
Degree of protection	IP20 / UL open	type
Frame size	FSD	
Net weight	20 kg (44.09 ll	b)
Dimensions		
Width	200 mm (7.87	in)
Height	472 mm (18.5	8 in)
Depth	248 mm (9.76	in)
	Standards	
Compliance with standards	UL, cUL, CE, C- SEMI F47, REA	Tick (RCM), EAC, KCC, CH
CE marking	EMC Directive 2004/108/EC, Low- Voltage Directive 2006/95/EC	
Converter lo	osses to IEC61800-	9-2*
Efficiency class	IE2	
Comparison with the reference converter (90% / 100%)	44.8 %	
Ⅰ ▲ 762.0 W (1.5 %)	894.0 W (1.7 %)	1,110.0 W (2.1 %)
439.0 W (0.9 %) 50%	488.0 W (0.9 %)	557.0 W (1.1 %)
333.0 W (0.6 %)	354.0 W (0.7 %) -●	
	50%	90% f

The percentage values show the losses in relation to the rated apparent power of the converter.

The diagram shows the losses for the points (as per standard IEC61800-9-2) of the relative torque generating current (I) over the relative motor stator frequency (f). The values are valid for the basic version of the converter without options/components.

*converted values

¹⁾The output current and HP ratings are valid for the voltage range 440V-480V

³⁾Typical value. More information can be found in the element group "Converter losses to IEC 61800-9-2" in this datasheet.