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Data sheet for SINAMICS G120X

Article No. :

6SL3220-1YE26-0UB0



Figure similar

Client order no. :
Order no. :
Offer no. :
Remarks :

Rate	ed data	
Input		
Number of phases	3 AC	
Line voltage	380 480 V +10	0 % -20 %
Line frequency	47 63 Hz	
Rated voltage	400V IEC	480V NEC
Rated current (LO)	24.50 A	21.30 A
Rated current (HO)	18.25 A	14.00 A
Output		
Number of phases	3 AC	
Rated voltage	400V IEC	480V NEC ¹⁾
Rated power (LO)	11.00 kW	15.00 hp
Rated power (HO)	7.50 kW	10.00 hp
Rated current (LO)	26.00 A	21.00 A
Rated current (HO)	18.00 A	14.00 A
Rated current (IN)	27.00 A	
Max. output current	35.00 A	
Pulse frequency	4 kHz	
Output frequency for vector control	0 200 Hz	
Output frequency for V/f control	0 550 Hz	

Overload capability

Low Overload (LO)

110% base load current IL for 60 s in a 300 s cycle time

High Overload (HO)

150% x base load current IH for 60 s within a 600 s cycle time

General tec	h. specifications	
Power factor λ	0.70 0.85	
Offset factor $\cos \phi$	0.96	
Efficiency η	0.98	
Sound pressure level (1m)	67 dB	
Power loss ³⁾	0.344 kW	
Filter class (integrated)	Unfiltered	
EMC category (with accessories)	without	
Safety function "Safe Torque Off"	without SIRIUS device (e.g. via S7- 1500F)	
Communication		

Communication

USS, Modbus RTU, BACnet MS/TP

ltem no. : Consignment no. : Project :

Inputs /	outputs
Standard digital inputs	
Number	6
Switching level: $0 \rightarrow 1$	11 V
Switching level: $1 \rightarrow 0$	5 V
Max. inrush current	15 mA
Fail-safe digital inputs	
Number	1
Digital outputs	
Number as relay changeover contact	2
Output (resistive load)	DC 30 V, 5.0 A
Number as transistor	0
Analog / digital inputs	
Number	2 (Differential input)
Resolution	10 bit
Switching threshold as digital input	
0 → 1	4 V
$1 \rightarrow 0$	1.6 V
Analog outputs	
Number	1 (Non-isolated output)
PTC/ KTY interface	
1 motor temperature sensor input, ser Thermo-Click, accuracy $\pm 5~^\circ\text{C}$	nsors that can be connected PTC, KTY and
Closed-loop co	ntrol techniques

Closed-loop cor	ntrol techniques
V/f linear / square-law / parameterizable	Yes
V/f with flux current control (FCC)	Yes
V/f ECO linear / square-law	Yes
Sensorless vector control	Yes
Vector control, with sensor	No
Encoderless torque control	No
Torque control, with encoder	No

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Ambien	t conditions
Standard board coating type	Class 3C2, according to IEC 60721-3-3: 2002
Cooling	Air cooling using an integrated fan
Cooling air requirement	0.018 m³/s (0.653 ft³/s)
Installation altitude	1,000 m (3,280.84 ft)
Ambient temperature	
Operation	-20 45 °C (-4 113 °F)
Transport	-40 70 °C (-40 158 °F)
Storage	-25 55 °C (-13 131 °F)
Relative humidity	
Max. operation	95 % At 40 °C (104 °F), condensation and icing not permissible
Conr	nections
Signal cable	
Conductor cross-section	0.15 1.50 mm² (AWG 24 AWG 16)
Line side	
Version	screw-type terminal
Conductor cross-section	1.50 16.00 mm² (AWG 16 AWG 6)
Motor end	
Version	Screw-type terminals
Conductor cross-section	1.50 16.00 mm² (AWG 16 AWG 6)
DC link (for braking resistor)	
PE connection	On housing with M4 screw
Max. motor cable length	
Shielded	150 m (492.13 ft)
Unshielded	300 m (984.25 ft)

1), EAC, KCC,	
EMC Directive 2004/108/EC, Low- Voltage Directive 2006/95/EC	
0 W (1.9 %)	
0 W (1.0 %)	

The percentage values show the losses in relation to the rated apparent power of the converter.

90% **f**

50%

The diagram shows the losses for the points (as per standard IEC61800-9-2) of the relative torque generating current (I) over the relative motor stator frequency (f). The values are valid for the basic version of the converter without options/components.

*converted values

¹⁾The output current and HP ratings are valid for the voltage range 440V-480V

³⁾ Typical value. More information can be found in the element group "Converter losses to IEC 61800-9-2" in this datasheet.