onsemi

Dual Supply, 2-Bit Voltage Translator / Buffer / Repeater / Isolator for I²C Applications

FXMA2102

Description

The FXMA2102 is a high-performance configurable dual-voltage-supply translator for bi-directional voltage translation over a wide range of input and output voltages levels.

Intended for use as a voltage translator between I²C–Bus complaint masters and slaves.

The device is designed so that the A port tracks the V_{CCA} level and the B port tracks the V_{CCB} level. This allows for bi–directional A/B port voltage translation between any two levels from 1.65 V to 5.5 V. V_{CCA} can equal V_{CCB} from 1.65 V to 5.5 V. The OE pin is referenced to V_{CCA}.

Either V_{CC} can be powered-up first. Internal power-down control circuits place the device in 3-state if either VCC is removed.

The two ports of the device have automatic direction sense capability. Either port may sense an input signal and transfer it as an output signal to the other port.

Features

- Bi-Directional Interface between Any Two Levels: 1.65 V to 5.5 V
- Direction Control not Needed
- System GPIO Resources Not Required when OE Tied to V_{CCA}
- I²C 400 pF Buffer / Repeater
- I²C Bus Isolation
- A/B Port V_{OL} = 175 mV (Typical), V_{IL} = 150 mV, I_{OL} = 6 mA
- Open-Drain Inputs / Outputs
- Accommodates Standard–Mode and Fast–Mode I²C–Bus Devices
- Supports I²C Clock Stretching & Multi-Master
- Fully Configurable: Inputs and Outputs Track V_{CC}
- Control Input (OE) Referenced to V_{CCA}.
- Non-Preferential Power-Up; Either V_{CC} May Be Powered-Up First
- Outputs Switch to 3-State if Either V_{CC} is at GND
- Tolerant Output Enable: 5 V
- Packaged in 8–Terminal Leadless MicroPak[™] (1.6 mm x 1.6 mm) and Ultrathin MLP (1.2 mm x 1.4 mm)
- ESD Protection Exceeds:
 - ◆ 5 kV HBM ESD (per JESD22–A114)
 - ◆ 2 kV CDM (per JESD22– C101)



UQFN8, 1.4x1.2, 0.4P CASE 523AS



UQFN8 1.6X1.6, 0.5P CASE 523AY

MARKING DIAGRAM



XN = Device Code

- &K = 2-Digits Lot Run Traceability Code
- &2 = 2-Digit Date Code
- &Z = Assembly Plant Code

ORDERING INFORMATION

See detailed ordering and shipping information on page 13 of this data sheet.

BLOCK DIAGRAM



Figure 1. Block Diagram, 1 of 2 Channels

PIN CONFIGURATION



Figure 2. MicroPak (Top-Through View)



Figure 3. UMLP (Top-Through View)

PIN DEFINITIONS

Pin No.	Name	Description
1	V _{CCA}	A-Side Power Supply
2, 3	A ₀ , A ₁	A-Side Inputs or 3-State Outputs
4	GND	Ground
5	OE	Output Enable Input (Referenced to V _{CCA})
6, 7	B ₁ , B ₀	B-Side Inputs or 3-State Outputs
8	V _{CCB}	B-Side Power Supply

TRUTH TABLE

Control	
OE	Outputs
LOW Logic Level	3-State
HIGH Logic Level	Normal Operation

1. If the OE pin is driven LOW, the FXMA2102 is disabled and the A₀, A₁, B₀, and B₁ pins (including dynamic drivers) are forced into 3-state.

ABSOLUTE MAXIMUM RATINGS

Symbol	Pa	arameter	Min	Мах	Unit
V _{CCA} , V _{CCB}	Supply Voltage		-0.5	7.0	V
V _{IN}	DC Input Voltage	A Port	-0.5	7.0	
		B Port	-0.5	7.0	
		Control Input (OE)	-0.5	7.0	
Vo	Output Voltage (Note 2)	A _n Outputs 3-State	-0.5	7.0	V
		B _n Outputs 3–State	-0.5	7.0	
		A _n Outputs Active	-0.5	V _{CCA} + 0.5 V	
		B _n Outputs Active	-0.5	V _{CCB} + 0.5 V	
Ι _{ΙΚ}	DC Input Diode Current	At V _{IN} < 0 V	-	50	mA
I _{OK}	DC Output Diode Current	At $V_0 < 0 V$	-	50	mA
		At $V_O > V_{CC}$	-	+50	
I _{OH} / I _{OL}	DC Output Source/Sink Current	•	-50	+50	mA
I _{CC}	DC V _{CC} or Ground Current per Sup	oly Pin	-	±100	mA
PD	Power Dissipation	At 400 KHz	-	0.129	mW
T _{STG}	Storage Temperature Range	•	65	+150	°C
ESD	Electrostatic Discharge Capability	Human Body Model, JESD22-A114	-	5	kV
		Charged Device Mode, JESD22-C101	-	2	

Stresses exceeding those listed in the Maximum Ratings table may damage the device. If any of these limits are exceeded, device functionality should not be assumed, damage may occur and reliability may be affected.

2. I_O absolute maximum rating must be observed.

RECOMMENDED OPERATING CONDITIONS

Symbol	Pa	Min	Max	Unit	
V_{CCA}, V_{CCB}	Power Supply Operating		1.65	5.50	V
V _{IN}	Input Voltage	A Port	0	5.5	V
		B Port	0	5.5	
		Control Input (OE)	0	V _{CCA}	
Θ_{JA}	Thermal Resistance	8-Lead MicroPak	-	279.0	°C/W
		8-Lead Ultrathin MLP	-	301.5	
T _A	Free Air Operating Temperature	-40	+85	°C	

Functional operation above the stresses listed in the Recommended Operating Ranges is not implied. Extended exposure to stresses beyond the Recommended Operating Ranges limits may affect device reliability.

3. All unused inputs and I/O pins must be held at V_{CCI} or GND

FUNCTIONAL DESCRIPTION

Power-Up/Power-Down Sequencing

FXM translators offer an advantage in that either V_{CC} may be powered up first. This benefit derives from the chip design. When either V_{CC} is at 0 V, outputs are in a high-impedance state. The control input (OE) is designed to track the V_{CCA} supply. A pull-down resistor tying OE to GND should be used to ensure that bus contention, excessive currents, or oscillations do not occur during power-up/ power-down. The size of the pull-down resistor is based upon the current-sinking capability of the device driving the OE pin.

- The recommended power-up sequence is:
 - 1. Apply power to the first V_{CC} .
 - 2. Apply power to the second V_{CC} .
 - 3. Drive the OE input HIGH to enable the device.
- The recommended power-down sequence is:
 - 1. Drive OE input LOW to disable the device.
 - 2. Remove power from either V_{CC} .
 - 3. Remove power from other V_{CC} .

NOTE:

4. Alternatively, the OE pin can be hardwired to V_{CCA} to save GPIO pins. If OE is hardwired to V_{CCA} , either V_{CC} can be powered up or down first.



APPLICATION CIRCUIT

Figure 4. Application Circuit

APPLICATION NOTES

The FXMA2102 has open-drain I/Os and requires external pull-up resistors on the four data I/O pins, as shown in Figure 4. If a pair of data I/O pins (A_n/B_n) is not used, both pins should be tied to GND (or both to V_{CC}). In this case, pull-down or pull-up resistors are not required. The recommended values for the pull-up resistors (RPU) are $1 k\Omega$ to $10 k\Omega$; however, depending on the total bus capacitance, the user is free to vary the pull-up resistor value to meet the maximum I^2C edge rate per the I^2C specification (UM10204 rev. 03, June 19, 2007). For example, the maximum edge rate (30% - 70%) during fast mode (400 kbit/s) is 300 ns. If bus capacitance is approaching the maximum 400 pF, low er the RPU value to keep the rise time below 300 ns (Fast Mode). Section 7.1 of the I^2C specification provides an excellent guideline for pull-up resistor sizing.

Theory of Operation

The FXMA2102 is designed for high–performance level shifting and buffer / repeating in an I^2C application. Figure 1 shows that each bi–directional channel contains two series–Npassgates and two dynamic drivers. This hybrid architecture is highly beneficial in an I^2C application where auto–direction is a necessity.

For example, during the following three I²C protocol events:

- · Clock Stretching
- Slave's ACK Bit (9th bit = 0) following a Master's Write Bit (8th bit = 0)
- Clock Synchronization and Multi Master Arbitration

The bus direction needs to change from master to slave to slave to master without the occurrence of an edge. If there is an I^2C translator between the master and slave in these examples, the I^2C translator must change direction when both A and B ports are LOW. The Npassgates can accomplish this task very efficiently because, when both A and B ports are LOW, the Npassgates act as a low resistive short between the two (A and B) ports.

Due to I²C's open-drain topology, I²C masters and slaves are not push/pull drivers. Logic LOWs are "pulled down" (Isink), while logic HIGHs are "let go" (3-state). For example, when the master lets go of SCL (SCL always comes from the master), the rise time of SCL is largely determined by the RC time constant, where $R = R_{PU}$ and C =the bus capacitance. If the FXMA2102 is attached to the master [on the A port] in this example, and there is a slave on the B port, the Npassgates act as a low resistive short between both ports until either of the port's $V_{CC}/2$ thresholds are reached. After the RC time constant has reached the $V_{CC}/2$ threshold of either port, the port's edge detector triggers both dynamic drivers to drive their respective ports in the LOW-to-HIGH (LH) direction, accelerating the rising edge. The resulting rise time resembles the scope shot in Figure 5. Effectively, two

distinct slew rates appear in rise time. The first slew rate (slower) is the RC time constant of the bus. The second slew rate (much faster) is the dynamic driver accelerating the edge.

If both the A and B ports of the translator are HIGH, a high–impedance path exists between the A and B ports because both the Npassgates are turned off. If a master or slave device decides to pull SCL or SDA LOW, that device's driver pulls dow n (I_{sink}) SCL or SDA until the edge reaches the A or B port $V_{CC}/2$ threshold. When either the A or B port threshold is reached, the port's edge detector triggers both dynamic drivers to drive their respective ports in the HIGH–to–LOW (HL) direction, accelerating the falling edge.



Figure 5. FXMA2102 Waveform C: 600 pF, R_{PU}: 2.2 K

Buffer / Repeater Performance

The FXMA2102 dynamic drivers have enough current sourcing capability to drive a 400 pF capacitive bus. This is beneficial for instances when an I^2C buffer / repeater is required. The I^2C specification stipulates a maximum bus capacitance of 400 pF. If an I^2C segment exceeds 400 pF, an I^2C buffer / repeater is required to split the segment into two segments, each of which is less than 400 pF. Figure 5 is a scope shot of an FXMA2102 driving a lumped load of 600 pF. Notice the (30% - 70%) rise time is only 112 ns ($R_{PU} = 2.2$ K). This is well below the maximum edge rate of 300 ns. Not only does the FXMA2102 drive 400 pF, but it also provides excellent headroom below the I^2C specification maximum edge rate of 300 ns.

V_{OL} vs. I_{OL}

The I²C specification mandates a maximum V_{IL} (I_{OL} of 3 mA) of $V_{CC} \cdot 0.3$ and a maximum V_{OL} of 0.4 V. If there is a master on the A port of an I²C translator w ith a V_{CC} of

1.65 V and a slave on the I²C translator B port w ith a V_{CC} of 3.3 V, the maximum V_{IL} of the master is $(1.65 \text{ V} \times 0.3)$ 495 mV. The slave could legally transmit a valid logic LOW of 0.4 V to the master.

If the I²C translator's channel resistance is too high, the voltage drop across the translator could present a V_{IL} to the master greater than 495 mV. To complicate matters, the I²C

specification states that 6 mA of I_{OL} is recommended for bus capacitances approaching 400 pF. More I_{OL} increases the voltage drop across the I²C translator. The I²C application benefits w hen I²C translators exhibit low V_{OL} performance. Figure 6 depicts typical FXMA2102 V_{OL} performance vs. the competition, given a 0.4 V V_{IL}.



Figure 6. V_{OL} vs. I_{OL}

I²C-Bus Isolation

The FXMA2102 supports I²C–Bus isolation for the following conditions:

- Bus isolation if bus clear
- Bus isolation if either $V_{CC}\, goes$ to ground

Bus Clear

Because the I²C specification defines the minimum SCL frequency of DC, the SCL signal can be held LOW forever; however, this condition shuts down the I²C bus. The I²C specification refers to this condition as "Bus Clear". In Figure 7, if slave #2 holds down SCL forever, the master and slave #1 are not able to communicate, because the FXMA2102 passes the SCL stuck–LOW condition from

slave #2 to slave #1 as well as the master. However, if the OE pin is pulled LOW (disabled), both ports (A and B) are 3–stated. This results in the FXMA2102 isolating slave #2 from the master and slave #1, allowing full communication between the master and slave #1.

Either V_{CC} to GND

If slave #2 is a camera that is suddenly removed from the I²C bus, resulting in V_{CCB} transitioning from a valid V_{CC} (1.65 V – 5.5 V) to 0 V, the FXMA2102 automatically forces SCL and SDA on both its A and B ports into 3–state. Once V_{CCB} has reached 0 V, full I²C communication between the master and slave #1 remains undisturbed.



DC ELECTRICAL CHARACTERISTICS (T_A = -40° C to $+85^{\circ}$ C)

Symbol	Parameter		Condition	V _{CCA} (V)	V _{CCB} (V)	Min	Max	Unit
V _{IHA}	High Level Input Voltage A	Data Inp	outs A _n	1.65 – 5.50	1.65 – 5.50	$V_{CCA} - 0.4$	-	V
		Control	Control Input OE		1.65 – 5.50	$0.7 \times V_{CCA}$	-	
V _{IHB}	High Level Input Voltage B	Data Inp	outs B _n	1.65 – 5.50	1.65 – 5.50	$V_{CCB} - 0.4$	-	V
V _{ILA}	Low Level Input Voltage A	Data Inp	outs A _n	1.65 – 5.50	1.65 – 5.50	-	0.4	V
		Control	Input OE	1.65 – 5.50	1.65 – 5.50	-	$0.3 \times V_{CCA}$	
V _{ILB}	Low Level Input Voltage B	Data Inp	outs B _n	1.65 – 5.50	1.65 – 5.50	-	0.4	V
V _{OL}	Low Level Output Voltage	V _{IL} = 0.1	15 V	1.65-5.50	1.65-5.50	-	0.4	V
		l _{OL} = 6 I	nA					
١L	Input Leakage Current	Control	Control Input OE, V _{IN} = V _{CCA} or GND		1.65 – 5.50	-	±1.0	μA
I _{OFF}	Power Off Leakage	A _n	V_{IN} or $V_O = 0$ V to 5.5 V	0	5.50	-	±2.0	μA
	Current	B _n	V_{IN} or $V_O = 0$ V to 5.5 V	5.50	0	-	±2.0	
I _{OZ}	3-State Output Leakage	A _n , B _n	V_{O} = 0 V to 5.5 V, OE = V_{IL}	5.50	5.50	-	±2.0	μA
	(Note 6)	A _n	V _O = 0 V to 5.5 V, OE = Don't Care	5.50	0	-	±2.0	
		B _n	V _O = 0 V to 5.5 V, OE = Don't Care	0	5.50	-	±2.0	
I _{CCA} /B	Quiescent Supply Current (Note 7, 8)	V _{IN} = V ₀	_{CCI} or GND, I _O = 0	1.65 – 5.50	1.65 – 5.50	-	5.0	μA
I _{CCZ}	Quiescent Supply Current (Note 7)	V _{IN} = V ₀	$_{CCI}$ or GND, $I_{O} = 0$, $OE = V_{IL}$	1.65 – 5.50	1.65 – 5.50	-	5.0	μA
I _{CCA}	Quiescent Supply	$V_{IN} = 5.5 \text{ V or GND}, I_O = 0,$ OE = Don't Care, B _n to A _n		0	1.65 – 5.50	-	-2.0	μA
	Current (Note 6)			1.65 – 5.50	0	-	2.0	
I _{CCB}	Quiescent Supply	V _{IN} = 5.	5 V or GND, I _O = 0,	1.65 – 5.50	0	-	-2.0	μA
	Current (Note 6)	OE = De	on't Care, A _n to B _n	0	1.65 – 5.50	-	2.0	

5. This table contains the output voltage for static conditions. Dynamic drive specifications are given in Dynamic Output Electrical Characteristics.

6. "Don't Care" indicates any valid logic level. 7. V_{CCI} is the V_{CC} associated with the input side. 8. Reflects current per supply, V_{CCA} or V_{CCB} .

DYNAMIC OUTPUT ELECTRICAL CHARACTERISTICS

			V _{CCO} (N	lote 10)		
		4.5 to 5.5 V	3.0 to 3.6 V	2.3 to 2.7 V	1.65 to 1.95 V	
Symbol	Parameter	Тур	Тур	Тур	Тур	Unit
t _{rise}	Output Rise Time; A Port, B Port (Note 11)	3	4	5	7	ns
t _{fall}	Output Fall Time; A Port, B Port (Note 12)	1	1	1	1	ns

OUTPUT RISE / **FALL TIME** (Output load: C_L = 50 pF, R_{PU} = 2.2 k Ω , push / pull driver, and T_A = -40°C to +85°C.)

9. Output rise and fall times guaranteed by design simulation and characterization; not production tested.

10. V_{CCO} is the V_{CC} associated with the output side. 11. See Figure 12.

12. See Figure 13.

DYNAMIC OUTPUT ELECTRICAL CHARACTERISTICS

MAXIMUM DATA RATE (Note 13) (Output load: C_L = 50 pF, R_{PU} = 2.2 k Ω , push / pull driver, and T_A = -40°C to +85°C.)

			Vo	СВ		
		4.5 to 5.5 V	3.0 to 3.6 V	2.3 to 2.7 V	1.65 to 1.95 V	
V _{CCA}	Direction	Min	Min	Min	Min	Unit
4.5 V to 5.5 V	A to B	37	26	19	10	MHz
	B to A	37	36	35	32	1
3.0 V to 3.6 V	A to B	36	25	18	10	MHz
	B to A	25	25	25	24	1
2.3 V to 2.7 V	A to B	35	25	18	10	MHz
	B to A	18	18	18	17	1
1.65 V to 1.95 V	A to B	32	24	17	10	MHz
	B to A	10	10	10	10	1

13.F-toggle guaranteed by design simulation; not production tested.

					Vc	СВ				
		4.5 to	5.5 V	3.0 to	3.6 V	2.3 to	2.7 V	1.65 to	9 1.95 V	
Symbol	Parameter	Тур	Max	Тур	Max	Тур	Max	Тур	Max	Unit
V _{CCA} = 4.5	to 5.5 V									
t _{PLH}	A to B	1	6	3	6	3	6	5	7	ns
	B to A	1	4	2	4	3	5	4	7	
t _{PHL}	A to B	2	4	3	5	4	6	9	10.5	ns
	B to A	2	4	2	5	2	6	5	7	
t _{PZL}	OE to A	4	5	6	10	5	9	7	15	ns
	OE to B	3	5	4	7	5	8	10	15	
t _{PLZ}	OE to A	65	100	65	105	65	105	65	105	ns
	OE to B	20	30	21	35	55	105	55	105	
t _{skew}	A Port, B Port (Note 14)	0.50	-	0.50	-	0.50	-	0.50	-	ns
V _{CCA} = 3.0	to 3.6 V									-
t _{PLH}	A to B	2.0	5.0	1.5	3.0	3.5	5.0	3.6	5.0	ns
	B to A	1.5	4.5	1.5	4.0	2.0	6.0	3.0	9.0	
t _{PHL}	A to B	2.0	4.0	2.0	4.0	2.0	5.0	4.3	7.5	ns
	B to A	2.0	5.3	2.0	4.0	2.0	5.0	3.0	5.0	
t _{PZL}	OE to A	4.0	8.0	5.0	9.0	6.0	11.0	7.0	15.0	ns
	OE to B	4.0	8.0	6.0	9.0	8.0	11.0	10.0	14.0	
t _{PLZ}	OE to A	100	115	100	115	100	115	100	115	ns
	OE to B	21	35	22	35	65	115	65	115	
t _{skew}	A Port, B Port (Note 14)	0.5	-	0.5	-	0.5	-	0.5	-	ns
V _{CCA} = 2.3	to 2.7 V									-
t _{PLH}	A to B	2.5	5.0	2.5	5.0	2.0	4.0	4.2	5.5	ns
	B to A	3.6	7.0	2.0	4.0	3.0	6.0	5.0	10.0	
t _{PHL}	A to B	2.0	5.0	2.0	5.0	2.0	5.0	3.0	6.0	ns
	B to A	6.0	7.5	4.0	5.5	2.0	5.0	3.0	6.0	
t _{PZL}	OE to A	5.0	10.0	5.0	10.0	6.0	12.0	9.0	18.0	ns
	OE to B	4.0	8.0	4.5	9.0	5.0	10.0	9.0	18.0	
t _{PLZ}	OE to A	100	115	100	115	100	115	100	115	ns
	OE to B	65	110	65	110	65	115	65	115	
t _{skew}	A Port, B Port (Note 14)	0.5	-	0.5	-	0.5	-	0.5	-	ns
V _{CCA} = 1.6	5 to 1.95 V									
t _{PLH}	A to B	4	7	4	7	5	8	5	10	ns
	B to A	4	8.5	4	5	4	5	5	10	
t _{PHL}	A to B	5	8	3	7	3	7	3	7	ns
	B to A	9.5	10.5	5	7.5	3	7	3	7	1
t _{PZL}	OE to A	11	15	11	14	8	28	14	23	ns
	OE to B	6	14	6	12	6	12	9	16]
t _{PLZ}	OE to A	75	115	75	115	75	115	75	115	ns
	OE to B	75	115	75	115	75	115	75	115	1

AC CHARACTERISTICS (Output load: $C_L = 50 \text{ pF}$, $R_{PU} = 2.2 \text{ k}\Omega$, and $T_A = -40^{\circ}\text{C}$ to $+85^{\circ}\text{C}$.)

14. Skew is the variation of propagation delay between output signals and applies only to output signals on the same port (A_n or B_n) and switching with the same polarity (LOW-to-HIGH or HIGH-to-LOW) *(see Figure 15)*. Skew is not tested.

_

0.5

_

0.5

_

0.5

ns

0.5

A Port, B Port (Note 14)

t_{skew}

CAPACITANCE (T_A = +25°C.)

Symbol	Parameter	Condition	Тур	Unit
C _{IN}	Input Capacitance Control Pin (OE)	$V_{CCA} = V_{CCB} = GND$	2.2	pF
C _{I/O}	Input/Output Capacitance, An, Bn	$V_{CCA} = V_{CCB} = 5.0 \text{ V}, \text{ OE} = \text{GND}, \text{ VA} = \text{VB} = 5.0 \text{ V}$	13.0	pF
C _{pd}	Power Dissipation Capacitance	V_{CCA} = V_{CCB} = 5.0 V, V_{IN} = 0 V or V_{CC},f = 400 KHz	13.5	pF



Figure 8. AC Test Circuit

Table 1. PROPAGATION DELAY TABLE

Test	Input Signal	Output Enable Control
t _{PLH} , t _{PHL}	Data Pulses	V _{CCA}
t _{PZL} (OE to A _n , B _n)	0 V	LOW to HIGH Switch
t _{PLZ} (OE to A _n , B _n)	0 V	HIGH to LOW Switch

Table 2. AC LOAD TABLE

Vcco	CL	RL
1.8 ± 0.15 V	50 pF	2.2 kΩ
2.5 ± 0.2 V	50 pF	2.2 kΩ
3.3 ± 0.3 V	50 pF	2.2 kΩ
5.0 ± 0.5 V	50 pF	2.2 kΩ

TIMING DIAGRAMS

















NOTES:

 $\begin{array}{l} \text{15. Input } t_R = t_F = 2.0 \text{ ns}, \ 10\% \ to \ 90\% \ at \ V_{IN} = 1.65 \ V \ to \ 1.95 \ V; \\ \text{Input } t_R = t_F = 2.0 \ ns, \ 10\% \ to \ 90\% \ at \ V_{IN} = 2.3 \ V \ to \ 2.7 \ V; \\ \text{Input } t_R = t_F = 2.5 \ ns, \ 10\% \ to \ 90\%, \ at \ V_{IN} = 3.0 \ V \ to \ 3.6 \ V \ only; \\ \text{Input } t_R = t_F = 2.5 \ ns, \ 10\% \ to \ 90\%, \ at \ V_{IN} = 4.5 \ V \ to \ 5.5 \ V \ only. \\ \ 16. V_{CCI} = V_{CCA} \ for \ control \ pin \ OE \ or \ V_{mi} = (V_{CCA} \ / \ 2). \end{array}$





Symbol	V _{CC}
V _{mi} (Note 16)	V _{CCI} / 2
V _{mo}	V _{CCO} / 2
V _X	0.1 x V _{CCO}
V _Y	V _{CCO} / 2









ORDERING INFORMATION

Part Number	Operating Temperature Range	Top Mark	Package	Packing Method [†]
FXMA2102L8X	−40 to +85°C	XN	8-Lead MicroPak, 1.6 mm Wide (Pb-Free)	5000 / Tape & Reel
FXMA2102UMX			8-Lead Ultrathin MLP, 1.2 mm x 1.4 mm (Pb-Free)	

+For information on tape and reel specifications, including part orientation and tape sizes, please refer to our Tape and Reel Packaging Specifications Brochure, BRD8011/D.

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DATE 31 AUG 2016





SIDE VIEW





NOTES:

- A. PACKAGE CONFORMS TO JEDEC MO-255 VARIATION UAAD.
- B. DIMENSIONS ARE IN MILLIMETERS.
- C. DIMENSIONS AND TOLERANCES PER ASME Y14.5M, 2009.
- D. LAND PATTERN RECOMMENDATION IS EXISTING INDUSTRY LAND PATTERN.



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