### **FEATURES**

- Input accepts virtually all logic standards:
  - Single-ended: SSTL, TTL, CMOS
  - · Differential: LVDS, HSTL, CML
- **■** Guaranteed AC parameters over temperature:
  - f<sub>MAX</sub> > 2.5Gbps (2.5GHz toggle)
  - $t_r / t_f < 200 ps$
  - Within-device skew < 50ps
  - Propagation delay < 400ps</li>
- Low power: 46mW/channel (typ)
- 3.0V to 3.6V power supply
- 100K LVPECL outputs
- Flow-through pinout and fully differential design
- Two channels in a 10-pin (3mm × 3mm) MSOP package

SuperLite™

Amendment: /0

#### DESCRIPTION

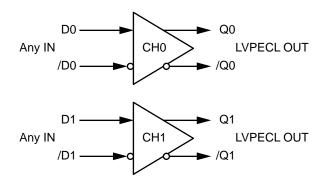
The SY55857L is a fully differential, high-speed dual translator optimized to accept any logic standard from single-ended TTL/CMOS to differential LVDS, HSTL, or CML and translate it to LVPECL. Translation is guaranteed for speeds up to 2.5Gbps (2.5GHz toggle frequency). The SY55857L does not internally terminate its inputs, as different interfacing standards have different termination requirements.

All support documentation can be found on Micrel's web site at www.micrel.com.

#### **APPLICATIONS**

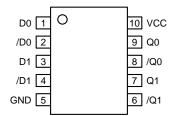
- High-speed logic
- Data communications systems
- **■** Wireless communications systems
- **■** Telecom systems

#### **FUNCTIONAL BLOCK DIAGRAM**



M9999-082306

# PACKAGE/ORDERING INFORMATION



10-Pin MSOP (K10-1)

# Ordering Information<sup>(1)</sup>

Part Number	Package Type	Operating Range	Package Marking	Lead Finish
SY55857LKI	K10-1	Industrial	857L	Sn-Pb
SY55857LKITR <sup>(2)</sup>	K10-1	Industrial	857L	Sn-Pb
SY55857LKG <sup>(3)</sup>	K10-1	Industrial	857L with Pb-Free bar line indicator	NiPdAu Pb-Free
SY55857LKGTR <sup>(2, 3)</sup>	K10-1	Industrial	857L with Pb-Free bar line indicator	NiPdAu Pb-Free

#### Notes:

- 1. Contact factory for die availability. Dice are guaranteed at  $T_A$  = 25°C, DC Electricals only.
- 2. Tape and Reel.
- 3. Pb-Free package recommended for new designs.

# **PIN DESCRIPTIONS**

Pin Number	Pin Name	Description	
D0, /D0	1, 2	Channel 0 Differential Inputs (clock or data). See Figure 2 for input structure. See "Input Interface" section for typical interface recommendations.	
D1, /D1	3, 4	Channel 1 Differential Inputs (clock or data). See Figure 2 for input structu See "Input Interface" section for typical interface recommendations.	
Q0, /Q0	9, 8	Channel 0 Differential 100k-compatible LVPECL Outputs. Terminate to V <sub>CC</sub> – 2V. See "LVPECL Output Termination" section. Outputs are low impedance, emitter-followers. For AC-coupled applications, a pull-down resistor is required on Q and /Q to ensure a DC current path to GND.	
Q1, /Q1	7, 6	Channel 1 Differential 100k-compatible LVPECL Outputs. Terminate to V <sub>CC</sub> – 2V. See "LVPECL Output Termination" section. Outputs are low impedance, emitter-followers. For AC-coupled applications, a pull-down resistor is required on Q and /Q to ensure a DC current path to GND.	
GND	5	Device Ground. Typically connected to Logic ground.	
V <sub>cc</sub>	10	Supply Voltage. Typically connect to +3.3V $\pm 10\%$ supply. Bypass with $0.01\mu F   0.1\mu F$ low ESR capacitors.	

# Absolute Maximum Ratings(1)

Power Supply Voltage (V <sub>CC</sub> )0.5V to +6	6.0V
Input Voltage (V <sub>IN</sub> )0.5V to V <sub>CC</sub> +	0.5V
Output Current (I <sub>OUT</sub> )	
Continuous50	0mA
Surge10	0mA
Lead Temperature (soldering, 20 sec.)+26	30°C
Storage Temperature Range (T <sub>S</sub> ) –65°C to +15	50°C

# Operating Ratings<sup>(2)</sup>

Power Supply Voltage (V <sub>CC</sub> )	+3.0V to +3.6V
Ambient Temperature Range (T <sub>A</sub> )	40°C to +85°C
Package Thermal Resistance <sup>(3)</sup>	
$MSOP(\theta_{JA})$	
Still-Air	113°C/W
500lpfm	96°C/W
$MSOP(\theta_{IC})$	
MSOP ( $\theta_{JC}$ )  Junction-to-Case	42°C/W

# DC ELECTRICAL CHARACTERISTICS(4)

 $T_A = -40^{\circ}C$  to +85°C; unless noted.

Symbol	Parameter	Condition	Min	Тур	Max	Units
V <sub>CC</sub>	Power Supply Voltage		3.0	3.3	3.6	V
I <sub>CC</sub>	Power Supply Current	Inputs/outputs open		28	45	mA

# INPUT ELECTRICAL CHARACTERISTICS(4)

 $V_{CC}$  = +3.0V to +3.6V; GND = 0V;  $T_A$  = -40°C to +85°C; unless noted.

Symbol	Parameter	Condition	Min	Тур	Max	Units
$V_{ID}$	Input Voltage Swing	See Figure 1a, V <sub>IN</sub> < 2.4V.	100			mV
		V <sub>IN</sub> < V <sub>CC</sub> +0.3V	200			mV
$V_{IH}$	Input HIGH Voltage				V <sub>CC</sub> +0.3	V
$V_{\rm IL}$	Input LOW Voltage		-0.3			V

# (100K) LVPECL OUTPUT CHARACTERISTICS<sup>(5)</sup>

 $V_{CC}$  = +3.0V to +3.6V; GND = 0V;  $T_A$  = -40°C to +85°C;  $R_L$  = 50 $\Omega$  to  $V_{CC}$  -2V, unless otherwise stated.

Symbol	Parameter	Condition	Min	Тур	Max	Units
V <sub>OL</sub>	Output LOW Voltage Q, /Q		V <sub>CC</sub> -1.945	V <sub>CC</sub> -1.820	V <sub>CC</sub> -1.695	V
V <sub>OH</sub>	Output HIGH Voltage Q, /Q		V <sub>CC</sub> -1.145	V <sub>CC</sub> -1.020	V <sub>CC</sub> -0.895	V
V <sub>OUT</sub>	Output Voltage Swing Q, /Q	See Figure 1a.	550	800		mV
V <sub>DIFF_OUT</sub>	Differential Output Voltage Swing Q, /Q	See Figure 1b.	1100	1600		mV <sub>pp</sub>

#### Notes:

- 1. Permanent device damage may occur if the ratings in "Absolute Maximum Ratings" section are exceeded. This is a stress rating only and functional operation is not implied at conditions other than those detailed in the operational sections of this data sheet. Exposure to absolute maximum ratings conditions for extended periods may affect device reliability.
- 2. The data sheet limits are not guaranteed if the device is operated beyond the operating ratings.
- 3. Package thermal resistance assumes exposed pad is soldered (or equivalent) to the device's most negative potential (GND) on the PCB.  $\psi_{JB}$  uses 4-layer  $\theta_{JA}$  in still air unless otherwise stated.
- 4. The specifications shown are valid after thermal equilibrium has been established.
- 5. 100K circuits are designed to meet the DC specifications shown in the above table after thermal equilibrium has been established.

### **AC ELECTRICAL CHARACTERISTICS**

 $V_{CC}$  = 3.3V ±10%;  $T_A$ = -40°C to +85°C;  $R_L$  = 50 $\Omega$  to  $V_{CC}$  -2V, unless otherwise stated.

Symbol	Parameter	Condition		Min	Тур	Max	Units
f <sub>MAX</sub>	Maximum Operating Frequency	V <sub>IN</sub> < 2.4V	NRZ Data	2.5			Gbps
	Note 6	V <sub>IN</sub> < 2.4V	Clock	2.5			GHz
		V <sub>IN</sub> < V <sub>CC</sub> +0.3V	NRZ Data	1.25			Gbps
		V <sub>IN</sub> < V <sub>CC</sub> +0.3V	Clock	1.25			GHz
t <sub>PD</sub>	Propagation Delay D-to-Q					400	ps
tSKEW	Within-Device-Skew (Differential)	Note 7				50	ps
	Part-to-Part Skew (Differential)	Note 8				200	ps
t <sub>JITTER</sub>	Random Jitter (RJ)	Note 9				1	ps <sub>RMS</sub>
	Deterministic Jitter (DJ)	Note 10				10	ps <sub>PP</sub>
	Total Jitter (TJ)	Note 11			1	10	ps <sub>PP</sub>
t <sub>r</sub> , t <sub>f</sub>	Output Rise/Fall Time 20% to 80%	At full output swing				200	ps

#### Notes:

- Clock frequency is defined as the maximum toggle frequency, and guaranteed for functionality only. Measured with a 750mV signal, 50% duty cycle and V<sub>OLT</sub> swing ≥ 400mV. High -frequency AC-parameters are guaranteed by design and characterization.
- 7. Within-device skew is measured between two different outputs under identical transitions.
- 8. Part-to-part skew is defined for two parts with identical power supply voltages at the same temperature and with no skew of the edges at the respective inputs.
- 9. Random jitter is measured with a K28.7 comma detect character pattern, measured at 2.5Gbps.
- 10. Deterministic jitter is measured at 2.5Gbps with both K28.5 and 2<sup>23</sup>–1 PRBS pattern.
- 11. Total jitter definition: with an ideal differential clock input of frequency ≤ f<sub>MAX</sub>, no more than one output edge in 10<sup>12</sup> output edges will deviate by more than the specified peak-to-peak jitter value.

#### SINGLE-ENDED AND DIFFERENTIAL SWINGS

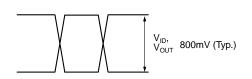


Figure 1a. Single-Ended Voltage Swing

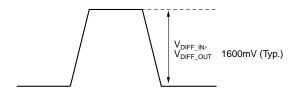


Figure 1b. Differential Voltage Swing

#### **FUNCTIONAL DESCRIPTION**

#### **Establishing Static Logic Inputs**

Do not leave unused inputs floating. Tie either the true or complement inputs to ground, but not both. A logic zero is achieved by connecting the complement input to ground with the true input floating. For a TTL input, tie a  $2.5 k\Omega$  resistor between the complement input and ground. See "Input Interface" section.

#### **Input Levels**

LVDS, CML and HSTL differential signals may be connected directly to the D inputs. Depending on the actual worst case voltage seen, performance of SY55857L varies as per the following table:

Input Voltage Range	Minimum Voltage Swing	Maximum Translation Speed
0 to 2.4V	100mV	2.5Gbps
0 to V <sub>CC</sub> +0.3	200mV	1.25Gbps

**Table 1. Input Voltage Swings** 

For LVDS applications, only point-to-point interfaces are supported. Due to the current required by the input structure shown in Figure 2, mutli-drop and multi-point architectures are not supported.

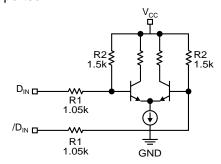


Figure 2. Simplified Input Structure

#### **INPUT INTERFACE**

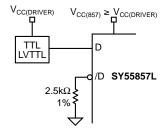


Figure 3. 3.3V "TTL"

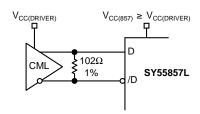


Figure 4. CML-DC Coupled

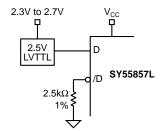


Figure 5. 2.5V "TTL"

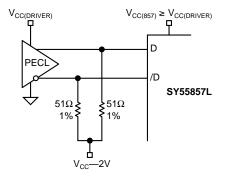


Figure 6. PECL-DC Coupled

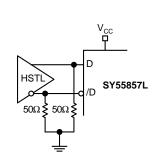


Figure 7. HSTL

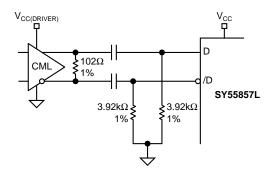


Figure 8. CML-AC Coupled Short Lines

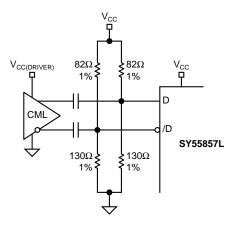


Figure 9. CML-AC Coupled Long Lines

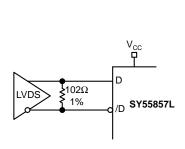


Figure 10. LVDS

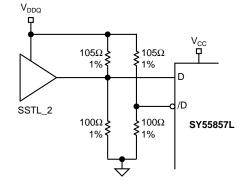


Figure 11. SSTL 2

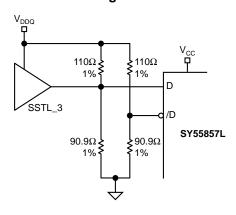


Figure 12. SSTL\_3

#### LVPECL OUTPUT TERMINATION

LVPECL output have very low output impedance (open emitter), and small signal swing which results in low EMI. LVPECL is ideal for driving  $50\Omega$  and  $100\Omega$ -controlled impedance transmission lines. There are several techniques in terminating the LVPECL output, as shown in Figures 13 through 15.

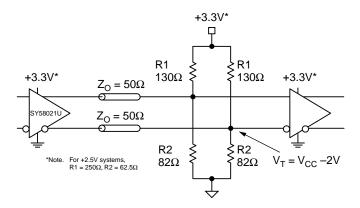


Figure 13. Parallel Termination-Thevenin Equivalent

#### Notes:

- 1. For +2.5V systems: R1 =  $250\Omega$ , R2 =  $62.5\Omega$ .
- 2. For +3.3V systems: R1 =  $130\Omega$ , R2 =  $82\Omega$ .

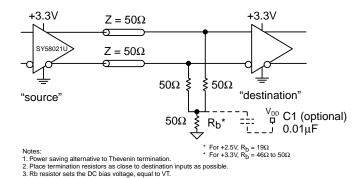


Figure 14. Three-Resistor "Y-Termination"

#### Notes:

- 1. Power-saving alternatives to Thevenin termination.
- 2. Place termination resistors as close to destination inputs as possible.
- 3. Rb resistor sets the DC bias voltage, equal to  $V_T$ .

For +2.5V systems:  $R_b = 19\Omega$ .

For +3.3V systems:  $R_b = 46\Omega$  to  $50\Omega$ .

4. C1 is an optional bypass capacitor intended to compensate for any  $t_{\text{r}}/t_{\text{f}}$  mismatches.

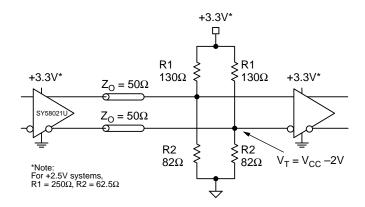


Figure 15. Terminating Unused I/O

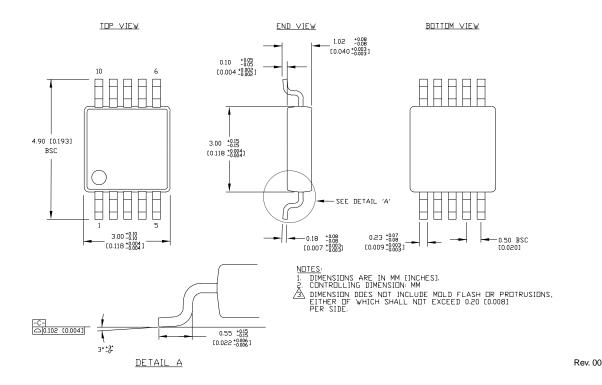
#### Notes:

- 1. Unused output (/Q) must be terminated to balance the output.
- 2. For +2.5V systems: R1 = 250 $\Omega$ , R2 = 62.5 $\Omega$ , R3 = 1.25k $\Omega$ , R4 = 1.2k $\Omega$

For +3.3V systems: R1 =  $130\Omega$ , R2 =  $82\Omega$ , R3 =  $1k\Omega$ , R4 =  $1.6k\Omega$ .

3. Unused output pairs (Q and /Q) may be left floating.

# 10-PIN MSOP (K10-1)



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