

# TMR1202 / TMR1208

MicroAmpere High Frequency Response Bipolar Latching Magnetic Switch Sensor

### Description

TMR1202/TMR1208 is a bipolar latching magnetic switch integrated the tunnel magnetoresistance (TMR) magnetic sensor and CMOS circuitry, which is able to detect the change of magnetic field and output high and low voltage signals for high accuracy position detection.

Unlike Hall/AMR sensors, TMR sensors with extremely high resistance values allows TMR1202/TMR1208 to achieve the supply current as low as 1.5  $\mu$ A while operating in the full-time power supply mode, and maintaining the response frequency of the magnetic signal is up to 5 kHz. Therefore, TMR1202/TMR1208 can provide true continuous detection of magnetic field signals, avoiding sampling errors from the traditional time-sharing power supply mode.

TMR1202/TMR1208 allows a wide range of operating supply voltages from 1.8 V to 5.5 V with excellent temperature characteristics, and can meet the requirements of most applications.

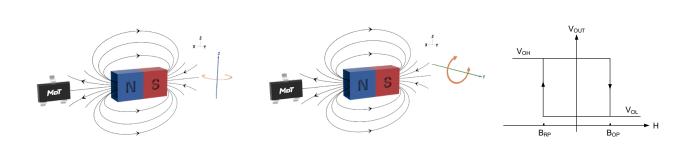
**TO92S** 



- Tunneling magnetoresistance (TMR) technology
- Low power consumption: supply current 1.5 μA
- High frequency response: up to 5 kHz
- Bipolar latching operation
- Wide range supply voltages: 1.8 V to 5.5 V
- · CMOS push-pull output
- · High sensitivity
- · Excellent temperature stability
- · High tolerance to external magnetic field interference
- RoHS & REACH compliant

#### **Applications**

- Utility meters: water, gas, and heat meters
- · Proximity switches
- Speed sensing
- · Linear and rotation position sensing
- · Wake-up switch



SOT23-3





Bipolar Latching Magnetic Switch Sensor

## **Selection Guide**

| Part Number  | Supply<br>Current | Response<br>Frequency | Operating Ambient<br>Temperature | Operating<br>Point | Release<br>Point | Package | Packing Form |
|--|-------------------|-----------------------|----------------------------------|--------------------|------------------|---------|--------------|
| TMR1202S   | 1.5 µA            | 1 kHz                 | -40 °C to 125 °C                 | 17 Gs              | -17 Gs           | SOT23-3 | Tape & Reel  |
| TMR1202T   | 1.5 µA            | 1 kHz                 | -40 °C to 125 °C                 | 17 Gs              | -17 Gs           | TO92S   | ESD Bag      |
| TMR1202HS  | 1.5 µA            | 5 kHz                 | -40 °C to 125 °C                 | 17 Gs              | -17 Gs           | SOT23-3 | Tape & Reel  |
| TMR1202HT  | 1.5 µA            | 5 kHz                 | -40 °C to 125 °C                 | 17 Gs              | -17 Gs           | TO92S   | ESD Bag      |
| TMR1202HTS   | 1.5 µA            | 5 kHz                 | -40 °C to 150 °C                 | 17 Gs              | -17 Gs           | SOT23-3 | Tape & Reel  |
| TMR1202HTT   | 1.5 µA            | 5 kHz                 | -40 °C to 150 °C                 | 17 Gs              | -17 Gs           | TO92S   | ESD Bag      |
| TMR1208S   | 1.5 µA            | 1 kHz                 | -40 °C to 125 °C                 | 5 Gs               | -5 Gs            | SOT23-3 | Tape & Reel  |
| TMR1208T   | 1.5 µA            | 1 kHz                 | -40 °C to 125 °C                 | 5 Gs               | -5 Gs            | TO92S   | ESD Bag      |
| Note: Please contact MultiDimension Technology local sales for customizing operating and release points. |                   |                       |                                  |                    |                  |         |              |

## Catalogue

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Microampere High Frequency Response Bipolar Latching Magnetic Switch Sensor

## 1. Functional Block Diagram

TMR1202/TMR1208 series switch chips are composed of TMR sensors and signal processing circuits. The TMR sensor detects external magnetic field, generates an analog voltage signal, and outputs a logical switch level after processing by the circuit as shown in Figure 1.

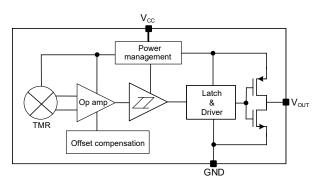


Figure 1. Block diagram

## 2. Switching Characteristics

The Figure 2 shows the sensing direction is parallel to the silkscreen surface of the package as shown by the arrow.

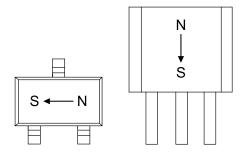


Figure 2. Sensing direction

The output is "High", when power is on at zero magnetic field. B is the external magnetic field along the sensing direction,  $B_{OP}$  is the operating point,  $B_{RP}$  is the release point, and hysteresis  $B_H$  is define as the difference between  $B_{OP}$  and  $B_{RP}$ .

The sensor outputs a low level, when the magnetic field along the sensing axis exceeds the operate point  $B_{OP}$ , and the device outputs a high level, when the magnetic field is reduced below the release point  $B_{RP}$  as shown in Figure 3.

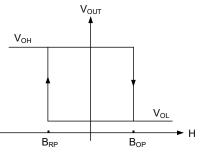


Figure 3. Switching characteristics

#### 3. Pin Configuration

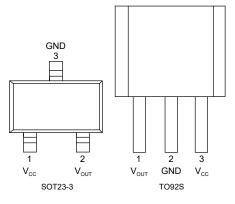


Figure 4. Pin configuration

| Pin Nu  | mber  | Name             | Function     |  |
|---------|-------|------------------|--------------|--|
| SOT23-3 | TO92S | Name             |              |  |
| 1 3     |       | V <sub>cc</sub>  | Power supply |  |
| 2       | 1     | V <sub>OUT</sub> | Output       |  |
| 3       | 2     | GND              | Ground       |  |





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### 4. Absolute Maximum Ratings

| Parameters                    | Symbol                                    | Min. | Max. | Unit | Applicable Part Number |
|-------------------------------|---|------|------|------|------------------------|
| Supply voltage                | V <sub>cc</sub>                           | -0.3 | 7    | V    | All parts              |
| Output current                | $I_{\text{SINK}}$ and $I_{\text{SOURCE}}$ | -    | 9    | mA   | All parts              |
| Magnetic flux density         | В   | -    | 4000 | Gs   | All parts              |
| ESD performance (HBM)         | V <sub>ESD</sub>                          | -    | 4    | kV   | All parts              |
| Operating embient temperature | т   | -40  | 125  | °C   | All parts              |
| Operating ambient temperature | T <sub>A</sub>                            | -50  | 150  | °C   | TMR1202HTS, TMR1202HTT |
| Storage ambient temperature   | T <sub>STG</sub>                          | -50  | 150  | °C   | All parts              |

Note:  $I_{SINK}$  is the current flowing through the high side MOSFET, when the high side MOSFET is turned on, and  $I_{SOURCE}$  is the current flowing through the low side MOSFET when the low side MOSFET is turned on.

## 5. Electrical Specifications

|  | 0.4.5                       |                                       |
|--|-----------------------------|---------------------------------------|
| $V_{CC} = 3.0 \text{ V}, I_{A} = 25 \text{ °C}, a$ | a 0.1 µF capacitor is conne | ected between V <sub>cc</sub> and GND |

| Parameter Symbol               |                 | Condition   | Min.                 | Тур. | Max.            | Unit | Applicable Part Number |
|--------------------------------|-----------------|-------------|----------------------|------|-----------------|------|------------------------|
| Supply voltage V <sub>cc</sub> |                 | operating   | 1.8                  | 3.0  | 5.5             | V    | All parts              |
| Output high voltage            | V <sub>он</sub> | RP status   | V <sub>cc</sub> -0.3 | -    | V <sub>cc</sub> | V    | All parts              |
| Output low voltage             | V <sub>OL</sub> | OP status   | 0                    | -    | 0.2             | V    | All parts              |
| Supply current                 | I <sub>cc</sub> | output open | 0.5                  | 1.5  | 2               | μA   | All parts              |
| Boononce frequency             | e frequency F   |             | 0 to 1000            |      |                 | Hz   | TMR1202x, TMR1208x     |
| Response frequency             |                 | -           | 0 to 5000            |      |                 | Hz   | TMR1202Hx, TMR1202HTx  |

## 6. Magnetic Specifications

 $V_{cc}$  = 3.0 V,  $T_{A}$  = 25 °C, a 0.1  $\mu F$  capacitor is connected between  $V_{cc}$  and GND

TMR1202x, TMR1202Hx, TMR1202HTx

| Parameter     | Symbol          | Min. | Тур. | Max. | Unit |
|---------------|-----------------|------|------|------|------|
| Operate point | B <sub>OP</sub> | 10   | 17   | 25   | Gs   |
| Release point | B <sub>RP</sub> | -25  | -17  | -10  | Gs   |
| Hysteresis    | B <sub>H</sub>  | 20   | -    | 50   | Gs   |

#### TMR1208x

| Parameter     | Symbol          | Min. | Тур. | Max. | Unit |
|---------------|-----------------|------|------|------|------|
| Operate point | B <sub>OP</sub> | 2    | 5    | 9    | Gs   |
| Release point | B <sub>RP</sub> | -9   | -5   | -2   | Gs   |
| Hysteresis    | B <sub>H</sub>  | 4    | -    | 18   | Gs   |





#### TMR1202 / TMR1208 Microampere High Frequency Response

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## 7. Typical Supply Voltage Characteristics

TMR1202x, TMR1202Hx, TMR1202HTx Supply Voltage Characteristics

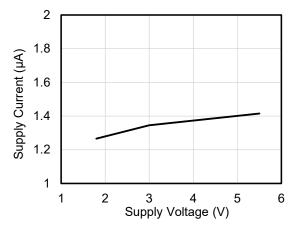


Figure 5. Supply current versus supply voltage ( $T_A=25^{\circ}C$ )

TMR1208x Supply Voltage Characteristics

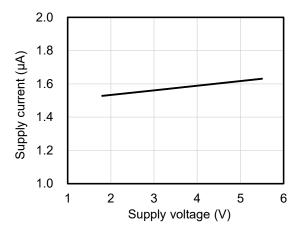


Figure 7. Supply current versus supply voltage ( $T_A=25^{\circ}C$ )

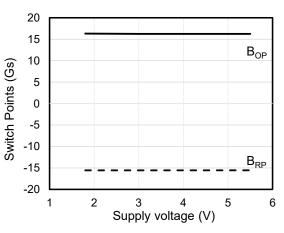


Figure 6. Switch points versus supply voltage ( $T_A=25^{\circ}C$ )

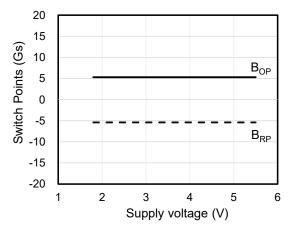


Figure 8. Switch points versus supply voltage ( $T_A=25^{\circ}C$ )



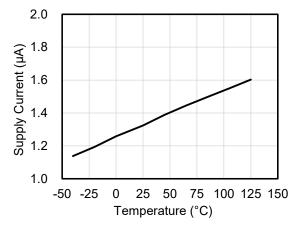


## TMR1202 / TMR1208

Microampere High Frequency Response Bipolar Latching Magnetic Switch Sensor

#### 8. Typical Temperature Characteristics

TMR1202x, TMR1202Hx Temperature Characteristics





#### TMR1202HTx Temperature Characteristics

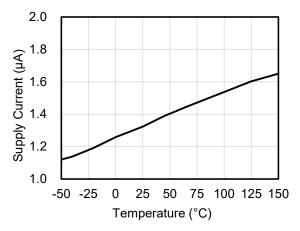
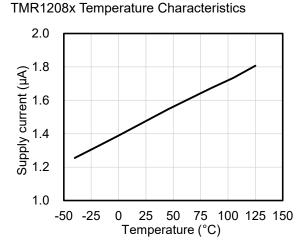


Figure 11. Supply current versus temperature ( $V_{cc}$  = 3 V)





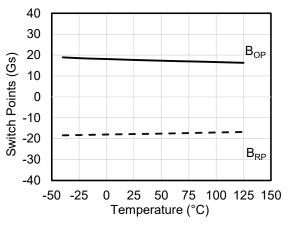


Figure 10. Switch points versus temperature ( $V_{cc}$  = 3 V)

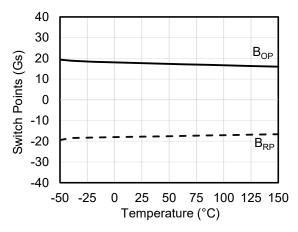
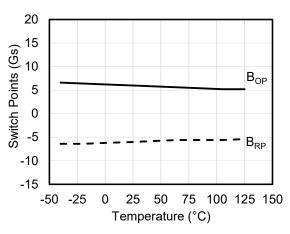
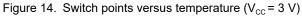


Figure 12. Switch points versus temperature ( $V_{CC}$  = 3 V)









## 9. Application Information

It is recommended to add a filter capacitor between the sensor power supply and ground (close to the sensor) to reduce external noise. As shown in Figure 15, the typical value is  $0.1 \,\mu$ F.

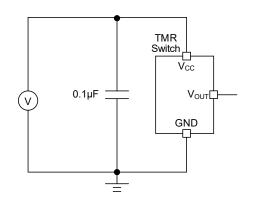


Figure 15. Application circuit diagram

The TMR1202/TMR1208 series sensor chips are not suitable for driving power loads. The general method of use is utilizing the output voltage of  $V_{OUT}$ pin as a signal to input the MCU or drive a triode or MOS as shown in Figure 16.

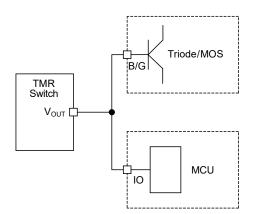


Figure 16. Application diagram for driving power load

Common failure conditions:

- The supply voltage exceeds the limit of absolute maximum ratings
- Absence of matching filter capacitor to power supply when the power supply is unstable, which can cause the product to restart repeatedly
- Using switch output  $V_{OUT}$  to control high-power relays, etc., and cause  $I_{SINK}$  and  $I_{SOURCE}$  exceeding the limit of absolute maximum ratings
- The external magnetic field exceeds the limit of absolute maximum ratings
- Operating in a humid environment for a long time, causing vapor penetration and increased power consumption
- Overheating when soldering
- Over bending of pins



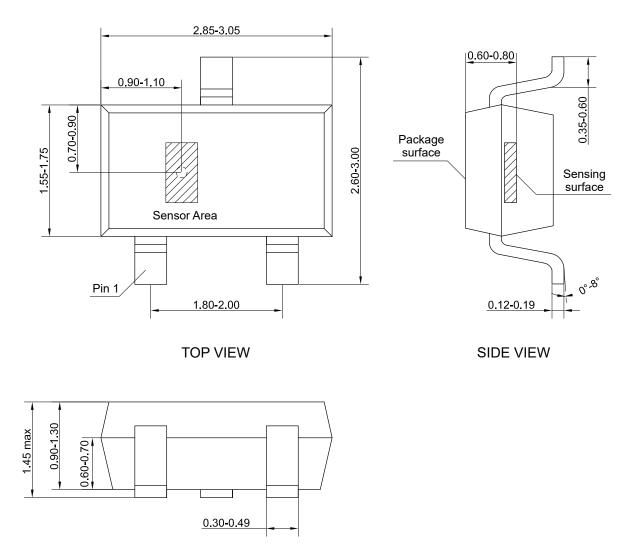


#### TMR1202 / TMR1208 Microampere High Frequency Response

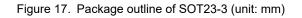
Bipolar Latching Magnetic Switch Sensor

### 10. Dimensions

#### SOT23-3 Package



SIDE VIEW







# TMR1202 / TMR1208

Microampere High Frequency Response Bipolar Latching Magnetic Switch Sensor

#### **TO92S Package**

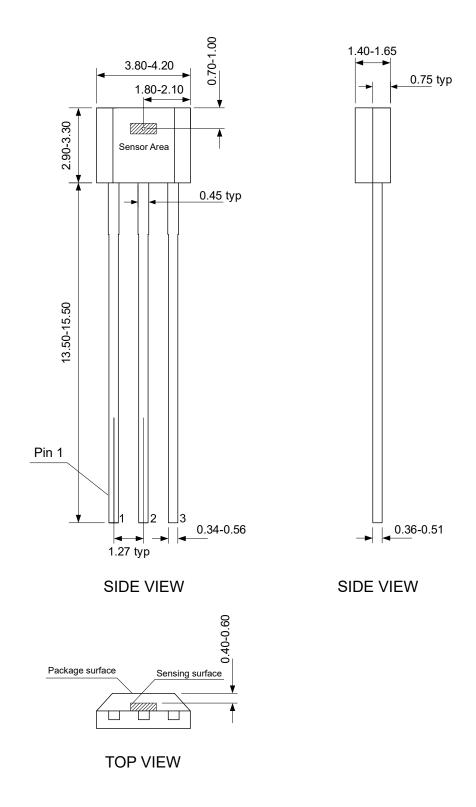


Figure 18. Package outline of TO92S (unit: mm)



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