Atlas Scientific Environmental Robotics

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# A-100 Analog Pressure Sensor

Reads

**Pressure (PSIG)** 

Range

Resolution

Accuracy

Connector

**Response** Time

Data protocol

Data format

Operating voltage

Durability

100 PSIG (689.47 kPa)

1mv (.025 psi /0.17 kPa)

< ± 0.1 PSI (0.689 kPa)

**Tinned leads** 

< 1 ms

Analog voltage

0.5 VDC - 4.5 VDC

**5 VDC** 

**IP67** 





### Absolute max ratings

VCC	5.5 VDC
Output current	0.45 mA
Operating temperature	-40°C – 105°C
Proof pressure	300 PSI (2,068 k
Burst pressure	900 PSI (6,205 k

#### **Power consumption**

5V

Pa) Pa) 6 mA



# **Operating principle**

Internally the pressure sensor uses a piezoresistive semiconducting element. The semiconducting element (*a silicon wafer*) changes its resistance in proportion to pressure. As the pressure increases the atomic spacing of the silicon atoms decreases, this in turn lowers the resistance of the silicon wafer.





Atmospheric pressure 1MΩ

10 PSI (68.947 kPa) 500KΩ

An on-board microcontroller monitors the resistance and temperature of the semiconducting element. By combining these two parameters, the microcontroller computes the pressure and convert it into an analog voltage.

#### Analog Output = 0.5 – 4.5 VDC

Pressure	Volts	Voltage to PSI equation
0 PSI (atmosphere)	0.5	$PSI = 25 \times (Volts) - 125$
20 psi	1.3	
40 psi	2.1	
60 psi	2.9	Voltage to kPa equation
80 psi	3.7	kPa = 172.37 x (Volts) - 86.185
100 psi	4.5	

When the sensor is not under any pressure it may read a slight negative pressure. It is common to see negative readings from **-0.1** to **-0.14** This is due to floating point error when the sensor is not under pressure and should be ignored.



# **Typical applications**







## Submerge



## **DO NOT submerge**



OK