SIEMENS

Data sheet 3RM1101-3AA14



Fail-safe direct starter, 3RM1, 500 V, 0 - 0.12 kW, 0.1 - 0.5 A, 110-230 V AC, screw/spring-type terminals

product brand name	SIRIUS
product category	Motor starter
product designation	Fail-safe direct starter
design of the product	With electronic overload protection and safety-related disconnection
product type designation	3RM1
General technical data	
equipment variant according to IEC 60947-4-2	3
product function	fail-safe direct starter
• intrinsic device protection	Yes
 for power supply reverse polarity protection 	Yes
suitability for operation device connector 3ZY12	No
insulation voltage rated value	500 V
overvoltage category	III
surge voltage resistance rated value	6 kV
maximum permissible voltage for protective separation	
 between main and auxiliary circuit 	500 V
between control and auxiliary circuit	250 V
shock resistance	6g / 11 ms
vibration resistance	1 6 Hz, 15 mm; 20 m/s², 500 Hz
operating frequency maximum	1 1/s
mechanical service life (operating cycles) typical	15 000 000
reference code according to IEC 81346-2	Q
Substance Prohibitance (Date)	03/01/2017
product function	
direct start	Yes
reverse starting	No
product function short circuit protection	No
Electromagnetic compatibility	
EMC emitted interference according to IEC 60947-1	class A
EMC immunity according to IEC 60947-1	Class A
conducted interference	
 due to burst according to IEC 61000-4-4 	3 kV / 5 kHz
 due to conductor-earth surge according to IEC 61000-4-5 	4 kV signal lines 2 kV
 due to conductor-conductor surge according to IEC 61000-4-5 	2 kV
 due to high-frequency radiation according to IEC 61000- 4-6 	10 V
field-based interference according to IEC 61000-4-3	10 V/m
electrostatic discharge according to IEC 61000-4-2	6 kV contact discharge / 8 kV air discharge
conducted HF interference emissions according to CISPR11	Class B for domestic, business and commercial environments; Class A for industrial environments at 110 V DC

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field-bound HF interference emission according to CISPR11	Class B for domestic, business and commercial environments; Class A for industrial environments at 110 V DC
Safety related data	
safety device type according to IEC 61508-2	Туре В
B10d value	1 300 000
Safety Integrity Level (SIL) according to IEC 61508	3
SIL Claim Limit (subsystem) according to EN 62061	SILCL 3
performance level (PL) according to EN ISO 13849-1	e
category according to EN ISO 13849-1	4
stop category according to EN 60204-1	0
Safe failure fraction (SFF)	99 %
average diagnostic coverage level (DCavg)	99 %
diagnostics test interval by internal test function maximum	600 s
function test interval maximum	1a
	l d
failure rate [FIT]	1 400 FIT
at rate of recognizable hazardous failures (λdd)	1 400 FIT
at rate of non-recognizable hazardous failures (λdu) PEUD with high demand rate goografing to EN 62064	16 FIT
PFHD with high demand rate according to EN 62061	2E-8 1/h
PFDavg with low demand rate according to IEC 61508	0
MTTFd	75 a
hardware fault tolerance according to IEC 61508	1
safe state	Load circuit open
protection class IP on the front according to IEC 60529	IP20
touch protection on the front according to IEC 60529	finger-safe
hardware fault tolerance according to IEC 61508 relating to ATEX	0
PFDavg with low demand rate according to IEC 61508 relating to ATEX	0.0005
PFHD with high demand rate according to EN 62061 relating to ATEX	5E-8 1/h
Safety Integrity Level (SIL) according to IEC 61508 relating to ATEX	SIL2
T1 value for proof test interval or service life according to IEC 61508 relating to ATEX	3 a
Main circuit	
Main circuit number of poles for main current circuit	3
number of poles for main current circuit	3 Hybrid
number of poles for main current circuit design of the switching contact adjustable current response value current of the current-	3 Hybrid 0.1 0.5 A
number of poles for main current circuit design of the switching contact adjustable current response value current of the current- dependent overload release	Hybrid 0.1 0.5 A
number of poles for main current circuit design of the switching contact adjustable current response value current of the current- dependent overload release minimum load [%]	Hybrid 0.1 0.5 A 20 %; from set rated current
number of poles for main current circuit design of the switching contact adjustable current response value current of the current- dependent overload release minimum load [%] type of the motor protection	Hybrid 0.1 0.5 A 20 %; from set rated current solid-state
number of poles for main current circuit design of the switching contact adjustable current response value current of the current- dependent overload release minimum load [%] type of the motor protection operating voltage rated value	Hybrid 0.1 0.5 A 20 %; from set rated current solid-state 48 500 V
number of poles for main current circuit design of the switching contact adjustable current response value current of the current- dependent overload release minimum load [%] type of the motor protection operating voltage rated value relative symmetrical tolerance of the operating voltage	Hybrid 0.1 0.5 A 20 %; from set rated current solid-state 48 500 V 10 %
number of poles for main current circuit design of the switching contact adjustable current response value current of the current- dependent overload release minimum load [%] type of the motor protection operating voltage rated value relative symmetrical tolerance of the operating voltage operating frequency 1 rated value	Hybrid 0.1 0.5 A 20 %; from set rated current solid-state 48 500 V 10 % 50 Hz
number of poles for main current circuit design of the switching contact adjustable current response value current of the current- dependent overload release minimum load [%] type of the motor protection operating voltage rated value relative symmetrical tolerance of the operating voltage operating frequency 1 rated value operating frequency 2 rated value	Hybrid 0.1 0.5 A 20 %; from set rated current solid-state 48 500 V 10 % 50 Hz 60 Hz
number of poles for main current circuit design of the switching contact adjustable current response value current of the current- dependent overload release minimum load [%] type of the motor protection operating voltage rated value relative symmetrical tolerance of the operating voltage operating frequency 1 rated value relative symmetrical tolerance of the operating frequency	Hybrid 0.1 0.5 A 20 %; from set rated current solid-state 48 500 V 10 % 50 Hz
number of poles for main current circuit design of the switching contact adjustable current response value current of the current- dependent overload release minimum load [%] type of the motor protection operating voltage rated value relative symmetrical tolerance of the operating voltage operating frequency 1 rated value operating frequency 2 rated value relative symmetrical tolerance of the operating frequency operational current	Hybrid 0.1 0.5 A 20 %; from set rated current solid-state 48 500 V 10 % 50 Hz 60 Hz 10 %
number of poles for main current circuit design of the switching contact adjustable current response value current of the current- dependent overload release minimum load [%] type of the motor protection operating voltage rated value relative symmetrical tolerance of the operating voltage operating frequency 1 rated value operating frequency 2 rated value relative symmetrical tolerance of the operating frequency operational current • at AC at 400 V rated value	Hybrid 0.1 0.5 A 20 %; from set rated current solid-state 48 500 V 10 % 50 Hz 60 Hz 10 %
number of poles for main current circuit design of the switching contact adjustable current response value current of the current- dependent overload release minimum load [%] type of the motor protection operating voltage rated value relative symmetrical tolerance of the operating voltage operating frequency 1 rated value operating frequency 2 rated value relative symmetrical tolerance of the operating frequency operational current • at AC at 400 V rated value • at AC-3 at 400 V rated value	Hybrid 0.1 0.5 A 20 %; from set rated current solid-state 48 500 V 10 % 50 Hz 60 Hz 10 % 0.5 A 0.5 A
number of poles for main current circuit design of the switching contact adjustable current response value current of the current- dependent overload release minimum load [%] type of the motor protection operating voltage rated value relative symmetrical tolerance of the operating voltage operating frequency 1 rated value operating frequency 2 rated value relative symmetrical tolerance of the operating frequency operational current • at AC at 400 V rated value	Hybrid 0.1 0.5 A 20 %; from set rated current solid-state 48 500 V 10 % 50 Hz 60 Hz 10 % 0.5 A 0.5 A 0.5 A
number of poles for main current circuit design of the switching contact adjustable current response value current of the current- dependent overload release minimum load [%] type of the motor protection operating voltage rated value relative symmetrical tolerance of the operating voltage operating frequency 1 rated value operating frequency 2 rated value relative symmetrical tolerance of the operating frequency operational current • at AC at 400 V rated value • at AC-3 at 400 V rated value • at AC-53a at 400 V at ambient temperature 40 °C rated value ampacity when starting maximum	Hybrid 0.1 0.5 A 20 %; from set rated current solid-state 48 500 V 10 % 50 Hz 60 Hz 10 % 0.5 A 0.5 A 0.5 A
number of poles for main current circuit design of the switching contact adjustable current response value current of the current- dependent overload release minimum load [%] type of the motor protection operating voltage rated value relative symmetrical tolerance of the operating voltage operating frequency 1 rated value operating frequency 2 rated value relative symmetrical tolerance of the operating frequency operational current • at AC at 400 V rated value • at AC-3 at 400 V rated value • at AC-53a at 400 V at ambient temperature 40 °C rated value ampacity when starting maximum operating power for 3-phase motors at 400 V at 50 Hz	Hybrid 0.1 0.5 A 20 %; from set rated current solid-state 48 500 V 10 % 50 Hz 60 Hz 10 % 0.5 A 0.5 A 0.5 A
number of poles for main current circuit design of the switching contact adjustable current response value current of the current- dependent overload release minimum load [%] type of the motor protection operating voltage rated value relative symmetrical tolerance of the operating voltage operating frequency 1 rated value operating frequency 2 rated value relative symmetrical tolerance of the operating frequency operational current • at AC at 400 V rated value • at AC-3 at 400 V rated value • at AC-53a at 400 V at ambient temperature 40 °C rated value ampacity when starting maximum	Hybrid 0.1 0.5 A 20 %; from set rated current solid-state 48 500 V 10 % 50 Hz 60 Hz 10 % 0.5 A 0.5 A 0.5 A
number of poles for main current circuit design of the switching contact adjustable current response value current of the current- dependent overload release minimum load [%] type of the motor protection operating voltage rated value relative symmetrical tolerance of the operating voltage operating frequency 1 rated value operating frequency 2 rated value relative symmetrical tolerance of the operating frequency operational current • at AC at 400 V rated value • at AC-3 at 400 V rated value • at AC-53a at 400 V at ambient temperature 40 °C rated value ampacity when starting maximum operating power for 3-phase motors at 400 V at 50 Hz	Hybrid 0.1 0.5 A 20 %; from set rated current solid-state 48 500 V 10 % 50 Hz 60 Hz 10 % 0.5 A 0.5 A 0.5 A
number of poles for main current circuit design of the switching contact adjustable current response value current of the current- dependent overload release minimum load [%] type of the motor protection operating voltage rated value relative symmetrical tolerance of the operating voltage operating frequency 1 rated value operating frequency 2 rated value relative symmetrical tolerance of the operating frequency operational current • at AC at 400 V rated value • at AC-3 at 400 V rated value • at AC-53a at 400 V at ambient temperature 40 °C rated value ampacity when starting maximum operating power for 3-phase motors at 400 V at 50 Hz Inputs/ Outputs	Hybrid 0.1 0.5 A 20 %; from set rated current solid-state 48 500 V 10 % 50 Hz 60 Hz 10 % 0.5 A 0.5 A 0.5 A
number of poles for main current circuit design of the switching contact adjustable current response value current of the current- dependent overload release minimum load [%] type of the motor protection operating voltage rated value relative symmetrical tolerance of the operating voltage operating frequency 1 rated value operating frequency 2 rated value relative symmetrical tolerance of the operating frequency operational current • at AC at 400 V rated value • at AC-3 at 400 V rated value • at AC-53a at 400 V at ambient temperature 40 °C rated value ampacity when starting maximum operating power for 3-phase motors at 400 V at 50 Hz Inputs/ Outputs input voltage at digital input	Hybrid 0.1 0.5 A 20 %; from set rated current solid-state 48 500 V 10 % 50 Hz 60 Hz 10 % 0.5 A 0.5 A 0.5 A 0.5 A
number of poles for main current circuit design of the switching contact adjustable current response value current of the current- dependent overload release minimum load [%] type of the motor protection operating voltage rated value relative symmetrical tolerance of the operating voltage operating frequency 1 rated value operating frequency 2 rated value relative symmetrical tolerance of the operating frequency operational current • at AC at 400 V rated value • at AC-3 at 400 V rated value • at AC-53a at 400 V at ambient temperature 40 °C rated value ampacity when starting maximum operating power for 3-phase motors at 400 V at 50 Hz Inputs/ Outputs input voltage at digital input • at DC rated value	Hybrid 0.1 0.5 A 20 %; from set rated current solid-state 48 500 V 10 % 50 Hz 60 Hz 10 % 0.5 A 0.5 A 0.5 A 0.5 A
number of poles for main current circuit design of the switching contact adjustable current response value current of the current- dependent overload release minimum load [%] type of the motor protection operating voltage rated value relative symmetrical tolerance of the operating voltage operating frequency 1 rated value relative symmetrical tolerance of the operating frequency operating frequency 2 rated value relative symmetrical tolerance of the operating frequency operational current	Hybrid 0.1 0.5 A 20 %; from set rated current solid-state 48 500 V 10 % 50 Hz 60 Hz 10 % 0.5 A 0.5 A 0.5 A 0.5 A 0 0.12 kW
number of poles for main current circuit design of the switching contact adjustable current response value current of the current- dependent overload release minimum load [%] type of the motor protection operating voltage rated value relative symmetrical tolerance of the operating voltage operating frequency 1 rated value operating frequency 2 rated value relative symmetrical tolerance of the operating frequency operational current	Hybrid 0.1 0.5 A 20 %; from set rated current solid-state 48 500 V 10 % 50 Hz 60 Hz 10 % 0.5 A 0.5 A 0.5 A 0.5 A 0 0.12 kW
number of poles for main current circuit design of the switching contact adjustable current response value current of the current- dependent overload release minimum load [%] type of the motor protection operating voltage rated value relative symmetrical tolerance of the operating voltage operating frequency 1 rated value operating frequency 2 rated value relative symmetrical tolerance of the operating frequency operational current • at AC at 400 V rated value • at AC-3 at 400 V rated value • at AC-53a at 400 V at ambient temperature 40 °C rated value ampacity when starting maximum operating power for 3-phase motors at 400 V at 50 Hz Inputs/ Outputs input voltage at digital input • at DC rated value • with signal <0> at DC • for signal <1> at DC input voltage at digital input	Hybrid 0.1 0.5 A 20 %; from set rated current solid-state 48 500 V 10 % 50 Hz 60 Hz 10 % 0.5 A 0.5 A 0.5 A 0.5 A 110 V 0 0.12 kW
number of poles for main current circuit design of the switching contact adjustable current response value current of the current- dependent overload release minimum load [%] type of the motor protection operating voltage rated value relative symmetrical tolerance of the operating voltage operating frequency 1 rated value operating frequency 2 rated value relative symmetrical tolerance of the operating frequency operational current • at AC at 400 V rated value • at AC-3 at 400 V rated value • at AC-53a at 400 V at ambient temperature 40 °C rated value ampacity when starting maximum operating power for 3-phase motors at 400 V at 50 Hz Inputs/ Outputs input voltage at digital input • at DC rated value • with signal <0> at DC • for signal <1> at DC input voltage at digital input • at AC rated value	Hybrid 0.1 0.5 A 20 %; from set rated current solid-state 48 500 V 10 % 50 Hz 60 Hz 10 % 0.5 A 0.5 A 0.5 A 0.5 A 110 V 110 V 110 V 110 V 110 V 110 V

• for signal <1> at DC • with signal <0> at DC input current at digital input with signal <0> at AC • at 110 V • at 230 V • at 230 V • at 230 V • at 230 V • at 110 V • at 230 V	
input current at digital input with signal <0> at AC • at 110 V • at 230 V input current at digital input for signal <1> at AC • at 110 V • at 230 V number of CO contacts for auxiliary contacts operational current of auxiliary contacts at AC-15 at 230 V maximum operational current of auxiliary contacts at DC-13 at 24 V maximum operational current of auxiliary contacts at DC-13 at 24 V maximum Control circuit/ Control type of voltage of the control supply voltage at 60 Hz rated value • at 50 Hz rated value relative negative tolerance of the control supply voltage at AC at 60 Hz relative positive tolerance of the control supply voltage at AC at 60 Hz control supply voltage 1 at AC • at 50 Hz • at 60 Hz control supply voltage frequency • 1 rated value • 2 rated value relative negative tolerance of the control supply voltage at DC relative positive tolerance of the control supply voltage at DC relative positive tolerance of the control supply voltage at DC relative positive tolerance of the control supply voltage at DC relative positive tolerance of the control supply voltage at DC relative positive tolerance of the control supply voltage at DC relative positive tolerance of the control supply voltage at DC initial value 0.85	
at 110 V at 230 V input current at digital input for signal <1> at AC at 110 V at 230 V 1.1 mA at 230 V number of CO contacts for auxiliary contacts operational current of auxiliary contacts at AC-15 at 230 V maximum operational current of auxiliary contacts at DC-13 at 24 V maximum operational current of auxiliary contacts at DC-13 at 24 V maximum operational current of auxiliary contacts at DC-13 at 24 V maximum operational current of auxiliary contacts at DC-13 at 24 V maximum operational current of auxiliary contacts at DC-13 at 24 V maximum operational current of auxiliary contacts at DC-13 at 24 V maximum operational current of auxiliary contacts at DC-13 at 24 V maximum operational current of auxiliary contacts at DC-13 at 24 V maximum operational current of auxiliary contacts at DC-13 at 24 V 1 A a Control supply voltage at AC at 50 Hz at 50 Hz at 20 Hz at	
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maximum operational current of auxiliary contacts at DC-13 at 24 V maximum Control circuit/ Control type of voltage of the control supply voltage o at 50 Hz rated value o at 60 Hz rated value relative negative tolerance of the control supply voltage at AC at 60 Hz relative positive tolerance of the control supply voltage at AC at 60 Hz control supply voltage 1 at AC o at 50 Hz o at 60 Hz control supply voltage frequency o 1 rated value o 2 rated value relative negative tolerance of the control supply voltage at DC relative positive tolerance of the control supply voltage at DC relative negative tolerance of the control supply voltage at DC control supply voltage 1 at DC rated value operating range factor control supply voltage rated value at DC o initial value 0.85	
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type of voltage of the control supply voltage control supply voltage at AC • at 50 Hz rated value • at 60 Hz rated value relative negative tolerance of the control supply voltage at AC at 60 Hz relative positive tolerance of the control supply voltage at AC at 60 Hz control supply voltage 1 at AC • at 50 Hz • at 60 Hz control supply voltage frequency • 1 rated value • 2 rated value • 2 rated value • 2 rated value control supply voltage 1 at DC rated value operating range factor control supply voltage rated value at DC • initial value • initial value 0.85	
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control supply voltage 1 at DC rated value operating range factor control supply voltage rated value at DC • initial value 0.85	
operating range factor control supply voltage rated value at DC • initial value 0.85	
DC	
• full-scale value 1.1	
operating range factor control supply voltage rated value at AC at 50 Hz	
• initial value 0.85	
• full-scale value 1.1	
operating range factor control supply voltage rated value at AC at 60 Hz	
• initial value 0.85	
• full-scale value 1.1	
control current at AC	
• at 110 V in standby mode of operation 8 mA	
• at 230 V in standby mode of operation 6 mA	
• at 110 V when switching on 40 mA	
• at 230 V when switching on 25 mA	
• at 110 V during operation 25 mA	
• at 230 V during operation 14 mA	
control current at DC	
• in standby mode of operation 4 mA	
• during operation 30 mA	
inrush current peak	
• at AC at 110 V 1 200 mA	
• at AC at 230 V 2 900 mA	
• at AC at 110 V at switching on of motor 1 200 mA	
at AC at 230 V at switching on of motor 2 900 mA duration of incush current peak	
duration of inrush current peak • at AC at 110 V 1 ms	
• at AC at 110 V • at AC at 230 V 1 ms	
TIIIS	

140 (440)/ 1 (11)	•
at AC at 110 V at switching on of motor	1 ms
at AC at 230 V at switching on of motor	1 ms
power loss [W] in auxiliary and control circuit	
• in switching state OFF	4.41W
— with bypass circuit	1.4 W
• in switching state ON	0.0011/
— with bypass circuit	3.22 W
Response times	
ON-delay time	90 120 ms
OFF-delay time	60 90 ms
Power Electronics	
operational current	
• at 40 °C rated value	0.5 A
• at 50 °C rated value	0.5 A
• at 55 °C rated value	0.5 A
at 60 °C rated value	0.5 A
Installation/ mounting/ dimensions	
mounting position	vertical, horizontal, standing (observe derating)
fastening method	screw and snap-on mounting onto 35 mm DIN rail
height	100 mm
width	23 mm
depth	142 mm
required spacing	
with side-by-side mounting	
— forwards	0 mm
— backwards	0 mm
— upwards	50 mm
— downwards	50 mm
— at the side	0 mm
• for grounded parts	0
— forwards	0 mm
— backwards	0 mm
— upwards — at the side	50 mm 4 mm
— at the side — downwards	4 mm
	50 111111
Ambient conditions	4 000 m; For densting one manual
installation altitude at height above sea level maximum	4 000 m; For derating see manual
ambient temperature	-25 +60 °C
during operation during storage	-25 +70 °C
during storage during transport	-40 +70 °C
during transport princeproperate enterprise apparation according to IEC.	
environmental category during operation according to IEC 60721	3K6 (no ice formation, only occasional condensation), 3C3 (no salt mist), 3S2 (sand must not get into the devices), 3M6
relative humidity during operation	10 95 %
air pressure according to SN 31205	900 1 060 hPa
Communication/ Protocol	
protocol is supported	
PROFINET IO protocol	No
PROFIsafe protocol	No
product function bus communication	No
protocol is supported AS-Interface protocol	No
Connections/ Terminals	
type of electrical connection	screw-type terminals for main circuit, spring-loaded terminals (push-in) for control circuit
for main current circuit	screw-type terminals
for auxiliary and control circuit	spring-loaded terminals (push-in)
wire length for motor unshielded maximum	100 m
type of connectable conductor cross-sections for main contacts	
• solid	1x (0,5 4 mm²), 2x (0,5 2,5 mm²)
finely stranded with core end processing	1x (0,5 4 mm²), 2x (0,5 1,5 mm²)
connectable conductor cross-section for main contacts	

0.5 4 mm²	
0.5 4 mm²	
0.5 1.5 mm²	
0.5 1 mm²	
0.5 1.5 mm²	
1x (0.5 1.5 mm²), 2x (0.5 1.5 mm²)	
1x (0,5 1,0 mm²), 2x (0,5 1,0 mm²)	
1x (0.5 1.5 mm²), 2x (0.5 1.5 mm²)	
1x (20 16), 2x (20 16)	
20 12	
20 16	
480 V	
0.5 A	
	EMC
	0.5 4 mm ² 0.5 1.5 mm ² 0.5 1 mm ² 0.5 1.5 mm ² 1x (0.5 1.5 mm ²), 2x (0.5 1.5 mm ²) 1x (0,5 1,0 mm ²), 2x (0,5 1,0 mm ²) 1x (0.5 1.5 mm ²), 2x (0.5 1.5 mm ²) 1x (20 16), 2x (20 16)



Confirmation









For use in hazardous locations Functional Safety/Safety of Machinery

Declaration of Conformity

other



Type Examination Certificate





Confirmation

Further information

Siemens has decided to exit the Russian market (see here).

https://press.siemens.com/global/en/pressrelease/siemens-wind-down-russian-business

Siemens is working on the renewal of the current EAC certificates.

Please contact your local Siemens office on the status of validity of the EAC certification if you intend to import or offer to supply these products to an EAC relevant market (other than the sanctioned EAEU member states Russia or Belarus).

Information on the packaging

https://support.industry.siemens.com/cs/ww/en/view/109813875

Information- and Downloadcenter (Catalogs, Brochures,...)

https://www.siemens.com/ic10

Industry Mall (Online ordering system)

https://mall.industry.siemens.com/mall/en/en/Catalog/product?mlfb=3RM1101-3AA14

Cax online generator

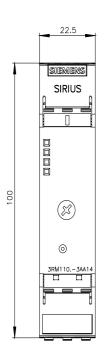
 $\underline{\text{http://support.automation.siemens.com/WW/CAXorder/default.aspx?lang=en\&mlfb=3RM1101-3AA14}$

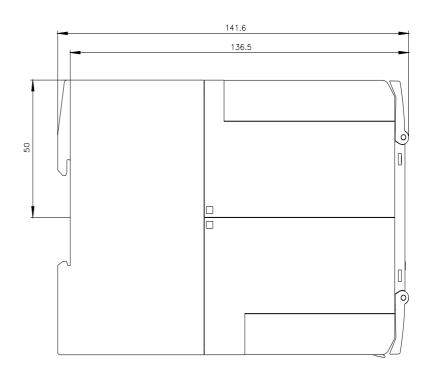
 $Service \& Support \ (Manuals, \ Certificates, \ Characteristics, \ FAQs, ...)$

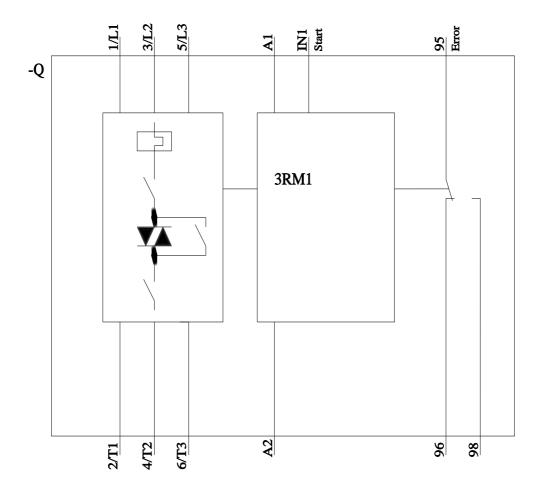
https://support.industry.siemens.com/cs/ww/en/ps/3RM1101-3AA14

 $Image\ database\ (product\ images,\ 2D\ dimension\ drawings,\ 3D\ models,\ device\ circuit\ diagrams,\ EPLAN\ macros,\ ...)$

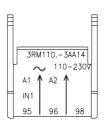
http://www.automation.siemens.com/bilddb/cax_de.aspx?mlfb=3RM1101-3AA14&lang=en

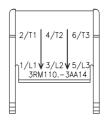












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