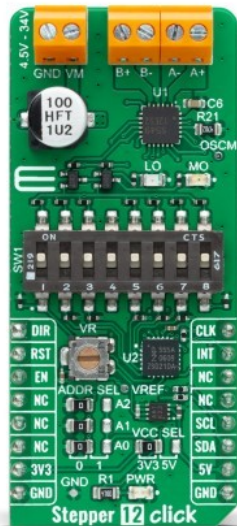


Stepper 12 Click



PID: MIKROE-5303

Stepper 12 Click is a compact add-on board that contains a bipolar stepper motor driver. This board features the [TB67S549FTG](#), a two-phase bipolar stepping motor driver from [Toshiba Semiconductor](#). It supports a PWM constant-current control drive without a current sense resistor for motor-current detection and allows full-step to 1/32 steps resolution for less motor noise and smoother control. It has a wide operating voltage range of 4.5V to 34V with an output current capacity of 1.2A maximum and several anomaly detection indicators. This Click board™ makes the perfect solution for small stepping motors in various applications such as office automation and commercial and industrial equipment.

Stepper 12 Click is supported by a [mikroSDK](#) compliant library, which includes functions that simplify software development. This [Click board™](#) comes as a fully tested product, ready to be used on a system equipped with the [mikroBUS™](#) socket.

How does it work?

Stepper 12 Click as its foundation uses the TB67S549FTG, a two-phase bipolar stepping motor driver designed to control one bipolar stepping motor with resistorless current sensing owing to the built-in function of Advanced Current Detect System (ACDS) from Toshiba Semiconductor. The TB67S549FTG incorporates low on-resistance DMOS FETs, which can deliver a 1.5A maximum current with a motor output voltage rating of 40V and integrated protection mechanisms such as over-current, over-temperature, and under-voltage lockout for error detection (LO LED indicator). It supports full-step to 1/32 steps resolution for less motor noise and smoother control, with Advanced Dynamic Mixed Decay (ADMD) built-in function that helps stabilize the current waveforms.

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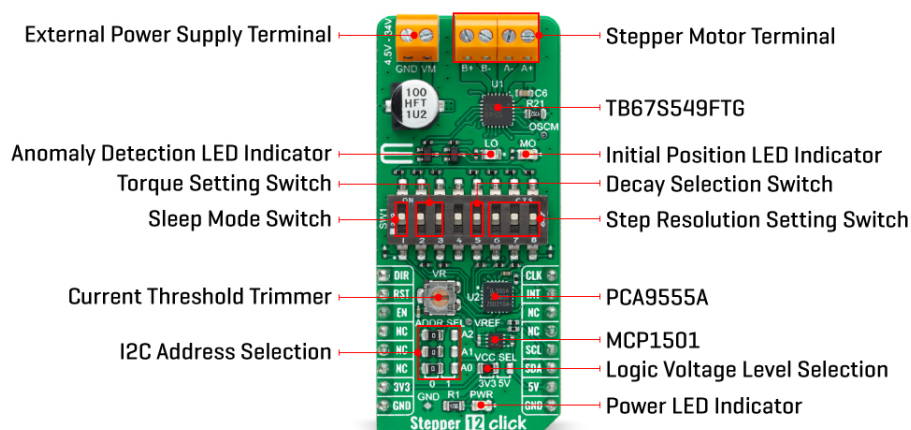
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Thanks to the many steps that TB67S549FTG supports, motor noise can be significantly reduced with smoother operation and more precise control. It is suited to a wide range of applications such as office automation, commercial, and industrial equipment using stepping motors supporting an operational temperature range covering 40°C to +85°C. The current value in the PWM constant-current mode is set by the reference voltage value obtained by the [MCP1501](#), a high-precision voltage regulator. Also, the current threshold point of the TB67S549FTG, alongside MCP1501, can be set manually using an onboard trimmer labeled VR.

In addition to the I2C communication, several GPIO pins connected to the mikroBUS™ socket pins are also used to forward the information to the MCU associated with the PCA9555A port expander. The [PCA9555A](#) also allows choosing the least significant bit (LSB) of its I2C slave address by positioning SMD jumpers labeled as ADDR SEL to an appropriate position marked as 0 and 1, alongside its interrupt feature routed to the INT pin of the mikroBUS™ socket.

The CLK clock signal, routed to the PWM pin of the mikroBUS™ socket, shifts the current step and electrical angle of the motor with its every up-edge, while the Enable pin, labeled as EN and routed to the CS pin of the mikroBUS™ socket, controls the state of the output A and B stepping motor drive channels. The normal constant current control is started by turning the motor drive ON (HIGH level), while by setting the motor drive OFF, the outputs are turned high impedance because the MOSFETs are set to OFF (LOW level). Besides, all circuits can be stopped using the Sleep function and thus enable power saving mode. A simple DIR pin routed to the AN pin on the mikroBUS™ socket allows MCU to manage the direction of the stepper motor (clockwise or counterclockwise), while the RST pin of the mikroBUS™ socket initializes an electrical angle in the internal counter to set an initial position. Achieving an initial position is indicated via onboard orange LED labeled as MO.

A specific addition to this Click board™ is a multifunctional switch that allows the user, by selecting a particular switch, to set appropriate features such as:

- 1 – Sleep Mode Activation
- 2 , 3 – Motor Torque Setting
- 5 – Decay Control
- 6 , 7 , 8 – Step Resolution Setting

In addition to this physical way of setting these functions, the user can select them digitally via the I2C interface.

The Stepper 12 Click supports an external power supply for the TB67S549FTG, which can be connected to the input terminal labeled as VM and should be within the range of 4.5V to 34V, while the stepper motor coils can be connected to the terminals labeled as B+, B-, A-, and A+.


This Click board™ can operate with both 3.3V and 5V logic voltage levels selected via the VCC SEL jumper. This way, it is allowed for both 3.3V and 5V capable MCUs to use communication lines properly. However, the Click board™ comes equipped with a library containing easy-to-use functions and an example code that can be used, as a reference, for further development.

Specifications

Type	Stepper
Applications	Can be used for small stepping motors in a wide range of applications such as office automation, commercial and industrial equipment
On-board modules	TB67S549FTG - two-phase bipolar stepping motor driver with resistorless current sensing thanks to Advanced Current Detect System (ACDS) from Toshiba Semiconductor
Key Features	Low power consumption, capable of controlling one bipolar stepping motor, PWM controlled constant-current drive, operational in full, half, quarter, 1/8, 1/16, and 1/32 step resolutions, built-in a mixed decay mode, anomaly detection functions, and more
Interface	GPIO,I2C
ClickID	No
Compatibility	mikroBUS™
Click board size	L (57.15 x 25.4 mm)
Input Voltage	3.3V or 5V,External

Pinout diagram

This table shows how the pinout on Stepper 12 Click corresponds to the pinout on the mikroBUS™ socket (the latter shown in the two middle columns).

Notes	Pin	 mikroBUS				Pin	Notes
Rotation Direction	DIR	1	AN	PWM	16	CLK	Step Clock
Electrical Angle Intilizing	RST	2	RST	INT	15	INT	Interrupt
Enable	EN	3	CS	RX	14	NC	
	NC	4	SCK	TX	13	NC	
	NC	5	MISO	SCL	12	SCL	I2C Clock
	NC	6	MOSI	SDA	11	SDA	I2C Data
Power Supply	3.3V	7	3.3V	5V	10	5V	Power Supply
Ground	GND	8	GND	GND	9	GND	Ground

Onboard settings and indicators

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Label	Name	Default	Description
LD1	PWR	-	Power LED Indicator
LD2	L0	-	Anomaly Detection LED Indicator
LD3	M0	-	Initial Position LED Indicator
JP1-JP3	ADDR SEL	Left	I2C Address Selection 0/1: Left position 0, Right position 1
JP4	VCC SEL	Left	Logic Level Voltage Selection 3V3/5V: Left position 3V3, Right position 5V
SW1	POS 1	Middle	Sleep Mode Activation Switch
SW1	POS 2-3	Middle	Motor Torque Setting Switch
SW1	POS 5	Middle	Mixed Decay Control Switch
SW1	POS 6-7-8	Middle	Step Resolution Setting Switch
VR	VR	-	Current Threshold Trimmer

Stepper 12 Click electrical specifications

Description	Min	Typ	Max	Unit
Supply Voltage VCC	3.3	-	5	V
External Supply Voltage VM	4.5	24	34	V
Maximum Output Voltage	-	-	40	V
Maximum Output Current	-	-	1.5	A
Maximum Step Clock Frequency	-	-	250	kHz
Operating Temperature Range	-20	+25	+85	°C

Software Support

We provide a library for the Stepper 12 Click as well as a demo application (example), developed using MikroElektronika [compilers](#). The demo can run on all the main MikroElektronika [development boards](#).

Package can be downloaded/installed directly from NECTO Studio Package Manager(recommended way), downloaded from our [LibStock™](#) or found on [Mikroe github account](#).

Library Description

This library contains API for Stepper 12 Click driver.

Key functions

- `stepper12_set_direction` This function sets the motor direction by setting the DIR pin logic state.

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- `stepper12_drive_motor` This function drives the motor for the specific number of steps at the selected speed.
- `stepper12_set_step_mode` This function sets the step mode resolution settings.

Example Description

This example demonstrates the use of the Stepper 12 Click board™ by driving the motor in both directions for a desired number of steps.

The full application code, and ready to use projects can be installed directly from NECTO Studio Package Manager(recommended way), downloaded from our [LibStock™](#) or found on [Mikroe github account](#).

Other Mikroe Libraries used in the example:

- MikroSDK.Board
- MikroSDK.Log
- Click.Stepper12

Additional notes and informations

Depending on the development board you are using, you may need [USB UART click](#), [USB UART 2 Click](#) or [RS232 Click](#) to connect to your PC, for development systems with no UART to USB interface available on the board. UART terminal is available in all MikroElektronika [compilers](#).

mikroSDK

This Click board™ is supported with [mikroSDK](#) - MikroElektronika Software Development Kit. To ensure proper operation of mikroSDK compliant Click board™ demo applications, mikroSDK should be downloaded from the [LibStock](#) and installed for the compiler you are using.

For more information about mikroSDK, visit the [official page](#).

Resources

[mikroBUS™](#)

[mikroSDK](#)

[Click board™ Catalog](#)

[Click boards™](#)

Downloads

[Stepper 12 click example on Libstock](#)

[TB67S549FTG datasheet](#)

[MCP1501 datasheet](#)

[PCA9555A datasheet](#)

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[Stepper 12 click schematic](#)

[Stepper 12 click 2D and 3D files](#)

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