



MOTOR FEEDBACK SYSTEMS



EES37-0KF0A017A | EES/EEM37

MOTOR FEEDBACK SYSTEMS



Ordering information

Туре	Part no.
EES37-0KF0A017A	1068811

Other models and accessories -> www.sick.com/EES_EEM37

Illustration may differ



Detailed technical data

Performance

Position	
Resolution per revolution	17 bit
System accuracy	\pm 240 ″, \pm 160 ″, nominal position, 25 °C, filter setting 21 kHz, Nominal position, 25 °C, filter setting 1 kHz $^{1)~1)}$
Signal noise (σ)	\pm 20 $^{\prime\prime}$ (nominal position, 25 °C, filter setting 21 kHz)
Number of the absolute ascertainable revolu- tions	
Available memory area	8,192 Byte
Measurement step per revolution	131,072

¹⁾ See diagram for error limits (default filter setting: 21 kHz).

Interfaces

Code sequence	Increasing, when turning the shaft For clockwise rotation, looking in direction "A" (see dimensional drawing)
Communication interface	HIPERFACE DSL [®]
Initialization time	Max. 500 ms ¹⁾
Measurement external temperature resis- tance	32-bit value, without prefix (1 $\Omega)$ 0 209.600 Ω $^{2)}$

¹⁾ From reaching a permitted operating voltage.

²⁾ Without sensor tolerance; at -17 °C ... +167 °C: NTC +-2K (103 GT); PTC+-3K (KTY84/130/PT1000).

Electrical data

Connection type	Male connector, 4-pin
Supply voltage	7 V 12 V
Warm-up time voltage ramp	Max. 180 ms ¹⁾
Current consumption	\leq 150 mA ²⁾
MTTF: mean time to dangerous failure	170 years (EN ISO 13849) ³⁾

 $^{1)}$ Duration of the voltage ramp between 0 and 7.0 V, see diagram "Current consumption" in the diagram section.

²⁾ Current rating applies when using interface circuit suggestions as shown in HIPERFACE DSL ® manual (8017595).

³⁾ This product is a standard product and does not constitute a safety component as defined in the Machinery Directive. Calculation based on nominal load of components, average ambient temperature 60°C, frequency of use 8760 h/a. All electronic failures are considered hazardous. For more information, see document no. 8015532.

Mechanical data

Shaft version	Tapered shaft
Dimensions	See dimensional drawing
Centering collar	Standard 1.5 mm
Weight	≤ 0.1 kg
Moment of inertia of the rotor	1 gcm ²
Operating speed	≤ 12,000 min ⁻¹
Angular acceleration	≤ 500,000 rad/s ²
Permissible radial shaft movement	± 0.15 mm
Permissible axial shaft movement	± 0.5 mm

Ambient data

Operating temperature range	-40 °C +115 °C ¹⁾
Storage temperature range	-40 °C +120 °C, without package
Relative humidity/condensation	85 %, Condensation not permitted
Resistance to shocks	100 g, 6 ms (according to EN 60068-2-27)
Frequency range of resistance to vibrations	50 g, 10 Hz 2,000 Hz (EN 60068-2-6)
EMC	According to EN 61000-6-2: 2016, EN 61000-6-4: 2006, IEC 6100-6-7: 2014 ²⁾
Enclosure rating	IP30, When cover is closed and mating connector is attached (IEC 60529-1) $^{3)}$

¹⁾ For typical values for self-heating, see diagram "Electrical self-heating" in the diagram section. see section "Mounting" in the operating instructions (8021414/8021265).

²⁾ According to the listed standards, EMC is guaranteed if the motor feedback system with mating connector inserted is connected to the central grounding point of the motor controller via a cable shield. If other shielding concepts are used, users must perform their own tests. Class A device.

 $^{\rm (3)}$ When using the strands (2079920).

Classifications

ECLASS 5.0	27270590
ECLASS 5.1.4	27270590
ECLASS 6.0	27270590
ECLASS 6.2	27270590
ECLASS 7.0	27270590
ECLASS 8.0	27270590
ECLASS 8.1	27270590
ECLASS 9.0	27270590
ECLASS 10.0	27273805
ECLASS 11.0	27273901
ECLASS 12.0	27273901
ETIM 5.0	EC001486
ETIM 6.0	EC001486
ETIM 7.0	EC001486
ETIM 8.0	EC001486
UNSPSC 16.0901	41112113

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Dimensional drawing (Dimensions in mm (inch))





Screw M4 not included (see under accessories)

- ① Measuring point for vibrations
- ② Design-related gap
- ③ Measuring point for operating temperature

④ Centering collar: Standard 1.5 mm; reduced 0.7 mm

Attachment specifications



Read out axial position: positive value shows movement of rotor away from the motor flange; negative value shows movement of rotor towards the motor flange

- ① Nominal position
- ② The size of the tolerance reduces the permissible wave movement, see data sheet
- ③ Threaded holes in accordance with DIN 13 with recesses in accordance with DIN 76 min. 1.05 x thread diameter

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PIN assignment

Supply / Communication pin assignment



Integrated in motor cable = J, K

PIN	Signal	Explanation
1		Not connected - no function
2	+U _S /DSL+	Supply 7 V 12 V
3	GND/DSL-	Ground connection
4		Not connected - no function
Recommended outer diameter of set of stranded wires: 4 mm +0/-1.5 mm		
Recommended mating connector: JST (GHR-04V-S)		

Temperature sensor pin assignment



Diagrams

Power consumption



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This diagram shows the switch-on current

Latency vs. filter frequency



Adjustable filter frequencies 21 kHz, 15 kHz, 10 kHz, 5 kHz und 1 kHz - Default setting 21 kHz Error limits

Typ. effect of temperature on accuracy, normed



Error limits



Typ. effect of axial position on accuracy, normed

Electrical self-heating



Recommended accessories

Other models and accessories → www.sick.com/EES_EEM37

	Brief description	Туре	Part no.
Nuts and scre	ws		
	100 pieces, Screws with Precote 85-8 coating; M4*14	BEF-MK-S03	2077358
	10 pieces, Screws with Precote 85-8 coating; M4*14	BEF-MK-S07	2088239
	500 pieces, Screws with Precote 85-8 coating; M4*14	BEF-MK-S08	2088240
Other mounting accessories			
	BEF-MW-PL	BEF-MW-PL	2084768
Others			
	 Connection type head A: Female connector, stranded wire, 4-pin, straight Connection type head B: Flying leads Signal type: HIPERFACE DSL[®] Cable: 0.2 m, 2-wire Description: HIPERFACE DSL[®], unshielded 	DOL-0B02-G0M2XC2	2079920

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Online data sheet

