



# 74VHC161

# 4-Bit Binary Counter with Asynchronous Clear

### **Features**

- High Speed: f<sub>MAX</sub> = 185MHz (Typ.) at T<sub>A</sub> = 25°C
- Synchronous counting and loading
- High-speed synchronous expansion
- Low power dissipation:  $I_{CC} = 4\mu A$  (Max.) at  $T_A = 25$ °C
- High noise immunity: V<sub>NIH</sub> = V<sub>NIL</sub> = 28% V<sub>CC</sub> (Min.)
- Power down protection provided on all inputs
- Low noise: V<sub>OLP</sub> = 0.8V (Max.)
- Pin and function compatible with 74HC161

## **General Description**

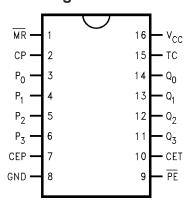
The VHC161 is an advanced high-speed CMOS device fabricated with silicon gate CMOS technology. It achieves the high-speed operation similar to equivalent Bipolar Schottky TTL while maintaining the CMOS low power dissipation. The VHC161 is a high-speed synchronous modulo-16 binary counter. This device is synchronously presettable for application in programmable dividers and have two types of Count Enable inputs plus a Terminal Count output for versatility in forming synchronous multistage counters. The VHC161 has an asynchronous Master Reset input that overrides all other inputs and forces the outputs LOW. An input protection circuit insures that 0V to 7V can be applied to the input pins without regard to the supply voltage. This device can be used to interface 5V to 3V systems and two supply systems such as battery backup. This circuit prevents device destruction due to mismatched supply and input voltages.

# **Ordering Information**

Order Number	Package Number	Package Description
74VHC161M	M16A	16-Lead Small Outline Integrated Circuit (SOIC), JEDEC MS-012, 0.150" Narrow
74VHC161SJ	M16D	16-Lead Small Outline Package (SOP), EIAJ TYPE II, 5.3mm Wide
74VHC161MTC	MTC16	16-Lead Thin Shrink Small Outline Package (TSSOP), JEDEC MO-153, 4.4mm Wide

Surface mount packages are also available on Tape and Reel. Specify by appending the suffix letter "X" to the ordering number.

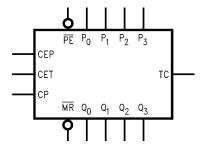
# **Connection Diagram**



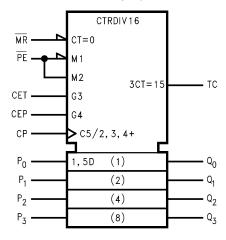
## **Pin Description**

Pin Names Description				
CEP	Count Enable Parallel Input			
CET	Count Enable Trickle Input			
СР	Clock Pulse Input			
MR	Asynchronous Master Reset Input			
P <sub>0</sub> –P <sub>3</sub>	Parallel Data Inputs			
PE	Parallel Enable Inputs			
Q <sub>0</sub> –Q <sub>3</sub>	Flip-Flop Outputs			
TC	Terminal Count Output			

# **Logic Symbols**



#### IEEE/IEC



#### **Functional Description**

The VHC161 counts in modulo-16 binary sequence. From state 15 (HHHH) it increments to state 0 (LLLL). The clock inputs of all flip-flops are driven in parallel through a clock buffer. Thus all changes of the Q outputs (except due to Master Reset of the VHC161) occur as a result of, and synchronous with, the LOW-to-HIGH transition of the CP input signal. The circuits have four fundamental modes of operation, in order of precedence: asynchronous reset, parallel load, count-up and hold. Five control inputs—Master Reset, Parallel Enable (PE), Count Enable Parallel (CEP) and Count Enable Trickle

(CET)—determine the mode of operation, as shown in the Mode Select Table. A LOW signal on  $\overline{\text{MR}}$  overrides all other inputs and asynchronously forces all outputs LOW. A LOW signal on  $\overline{\text{PE}}$  overrides counting and allows information on the Parallel Data  $(P_n)$  inputs to be loaded into the flip-flops on the next rising edge of CP. With  $\overline{\text{PE}}$  and  $\overline{\text{MR}}$  HIGH, CEP and CET permit counting when both are HIGH. Conversely, a LOW signal on either CEP or CET inhibits counting.

The VHC161 uses D-type edge-triggered flip-flops and changing the PE, CEP and CET inputs when the CP is in either state does not cause errors, provided that the recommended setup and hold times, with respect to the rising edge of CP, are observed.

The Terminal Count (TC) output is HIGH when CET is HIGH and counter is in state 15. To implement synchronous multistage counters, the TC outputs can be used with the CEP and CET inputs in two different ways.

Figure 1 shows the connections for simple ripple carry, in which the clock period must be longer than the CP to TC delay of the first stage, plus the cumulative CET to TC delays of the intermediate stages, plus the CET to CP setup time of the last stage. This total delay plus setup time sets the upper limit on clock frequency. For faster clock rates, the carry lookahead connections shown in Figure 2 are recommended. In this scheme the ripple delay through the intermediate stages commences with the same clock that causes the first stage to tick over from max to min to start its final cycle. Since this final cycle requires 16 clocks to complete, there is plenty of time for the ripple to progress through the intermediate stages. The critical timing that limits the clock period is the CP to TC delay of the first stage plus the CEP to CP setup time of the last stage. The TC output is subject to decoding spikes due to internal race conditions and is therefore not recommended for use as a clock or asynchronous reset for flip-flops, registers or counters.

#### **Logic Equations:**

Count Enable = CEP • CET • PE

$$TC = Q_0 \cdot Q_1 \cdot Q_2 \cdot Q_3 \cdot CET$$

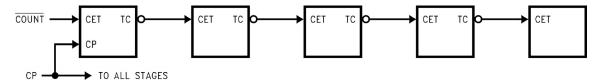


Figure 1. Multistage Counter with Ripple Carry

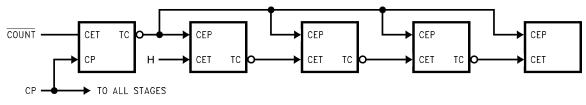


Figure 2. Multistage Counter with Lookahead Carry

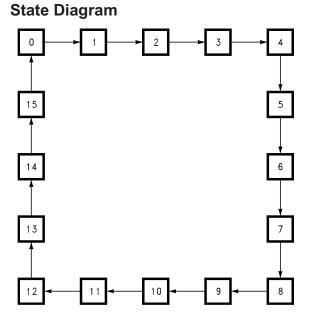
### **Mode Select Table**

MR	PE	CET	СЕР	Action on the Rising Clock Edge ( )
L	Х	Х	Х	Reset (Clear)
Н	L	Х	Х	Load $(P_n \rightarrow Q_n)$
Н	Н	Н	Н	Count (Increment)
Н	Н	L	Х	No Change (Hold)
Н	Н	Х	L	No Change (Hold)

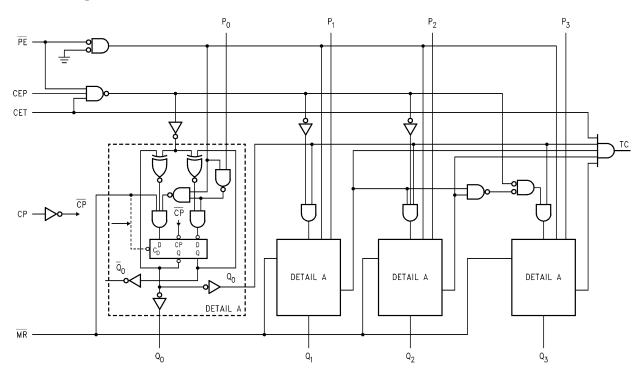
H = HIGH Voltage Level

L = LOW Voltage Level

X = Immaterial



# **Block Diagram**



Please note that this diagram is provided only for the understanding of logic operations and should not be used to estimate propagation delays.

# **Absolute Maximum Ratings**

Stresses exceeding the absolute maximum ratings may damage the device. The device may not function or be operable above the recommended operating conditions and stressing the parts to these levels is not recommended. In addition, extended exposure to stresses above the recommended operating conditions may affect device reliability. The absolute maximum ratings are stress ratings only.

Symbol	Parameter	Rating
V <sub>CC</sub>	Supply Voltage	-0.5V to +7.0V
V <sub>IN</sub>	DC Input Voltage	-0.5V to +7.0V
V <sub>OUT</sub>	DC Output Voltage	–0.5V to V <sub>CC</sub> + 0.5V
I <sub>IK</sub>	Input Diode Current	–20mA
I <sub>OK</sub>	Output Diode Current	±20mA
I <sub>OUT</sub>	DC Output Current	±25mA
I <sub>CC</sub>	DC V <sub>CC</sub> / GND Current	±50mA
T <sub>STG</sub>	Storage Temperature	–65°C to +150°C
T <sub>L</sub>	Lead Temperature (Soldering, 10 seconds)	260°C

# Recommended Operating Conditions<sup>(1)</sup>

The Recommended Operating Conditions table defines the conditions for actual device operation. Recommended operating conditions are specified to ensure optimal performance to the datasheet specifications. Fairchild does not recommend exceeding them or designing to absolute maximum ratings.

Symbol	Parameter	Rating
V <sub>CC</sub>	Supply Voltage	2.0V to +5.5V
V <sub>IN</sub>	Input Voltage	0V to +5.5V
V <sub>OUT</sub>	Output Voltage	0V to V <sub>CC</sub>
T <sub>OPR</sub>	Operating Temperature	-40°C to +85°C
t <sub>r</sub> , t <sub>f</sub>	Input Rise and Fall Time,	
	$V_{CC} = 3.3V \pm 0.3V$	0ns/V ~ 100ns/V
	$V_{CC} = 5.0V \pm 0.5V$	0ns/V ~ 20ns/V

#### Note:

1. Unused inputs must be held HIGH or LOW. They may not float.

# **DC Electrical Characteristics**

					Т	- A = 25°	С	1	40°C to 5°C	
Symbol	Parameter	V <sub>CC</sub> (V)	Con	Conditions		Тур.	Max.	Min.	Max.	Units
V <sub>IH</sub>	HIGH Level Input	2.0			1.50			1.50		V
	Voltage	3.0-5.5			0.7 x V <sub>CC</sub>			0.7 x V <sub>CC</sub>		
V <sub>IL</sub>	LOW Level Input	2.0					0.50		0.50	V
	Voltage	3.0-5.5					0.3 x V <sub>CC</sub>		0.3 x V <sub>CC</sub>	
V <sub>OH</sub>	HIGH Level	2.0	$V_{IN} = V_{IH}$	$I_{OH} = -50\mu A$	1.9	2.0		1.9		V
	Output Voltage		or V <sub>IL</sub>		2.9	3.0		2.9		
		4.5			4.4	4.5		4.4		
		3.0		$I_{OH} = -4mA$	2.58			2.48		
		4.5		$I_{OH} = -8mA$	3.94			3.80		
V <sub>OL</sub>	LOW Level	2.0	$V_{IN} = V_{IH}$	$I_{OL} = 50\mu A$		0.0	0.1		0.1	V
	Output Voltage	3.0	or V <sub>IL</sub>			0.0	0.1		0.1	
		4.5				0.0	0.1		0.1	
		3.0		I <sub>OL</sub> = 4mA			0.36		0.44	
		4.5		I <sub>OL</sub> = 8mA			0.36		0.44	
I <sub>IN</sub>	Input Leakage Current	0–5.5	V <sub>IN</sub> = 5.5V	or GND			±0.1		±1.0	μA
I <sub>CC</sub>	Quiescent Supply Current	5.5	$V_{IN} = V_{CC}$	or GND			4.0		40.0	μA

# **Noise Characteristics**

				$T_A = 25^{\circ}C$		
Symbol	Parameter	V <sub>CC</sub> (V)	Conditions	Тур.	Limits	Units
V <sub>OLP</sub> <sup>(2)</sup>	Quiet Output Maximum Dynamic V <sub>OL</sub>	5.0	C <sub>L</sub> = 50pF	0.4	0.8	V
V <sub>OLV</sub> <sup>(2)</sup>	Quiet Output Minimum Dynamic V <sub>OL</sub>	5.0	C <sub>L</sub> = 50pF	-0.4	-0.8	V
V <sub>IHD</sub> <sup>(2)</sup>	Minimum HIGH Level Dynamic Input Voltage	5.0	C <sub>L</sub> = 50pF		3.5	V
V <sub>ILD</sub> <sup>(2)</sup>	Maximum LOW Level Dynamic Input Voltage	5.0	C <sub>L</sub> = 50pF		1.5	V

#### Note:

2. Parameter guaranteed by design.

### **AC Electrical Characteristics**

				T <sub>A</sub> = 25°C			40° to 5°C		
Symbol	Parameter	V <sub>CC</sub> (V)	Conditions	Min.	Тур.	Max.	Min.	Max.	Units
t <sub>PLH</sub> , t <sub>PHL</sub>	Propagation Delay	3.3 ± 0.3	$C_L = 15pF$		8.3	12.8	1.0	15.0	ns
	Time (CP-Q <sub>n</sub> )		$C_L = 50pF$		10.8	16.3	1.0	18.5	
		5.0 ± 0.5	C <sub>L</sub> = 15pF		4.9	8.1	1.0	9.5	ns
			$C_L = 50pF$		6.4	10.1	1.0	11.5	
t <sub>PLH</sub> , t <sub>PHL</sub>	Propagation Delay	3.3 ± 0.3	C <sub>L</sub> = 15pF		8.7	13.6	1.0	16.0	ns
	Time (CP–TC, Count)		$C_L = 50pF$		11.2	17.1	1.0	19.5	
		5.0 ± 0.5	$C_L = 15pF$		4.9	8.1	1.0	9.5	ns
			$C_L = 50pF$		6.4	10.1	1.0	11.5	
t <sub>PLH</sub> , t <sub>PHL</sub>	Propagation Delay	3.3 ± 0.3	C <sub>L</sub> = 15pF		11.0	17.2	1.0	20.0	ns
	Time (CP-TC, Load)		$C_L = 50pF$		13.5	20.7	1.0	23.5	
		5.0 ± 0.5	C <sub>L</sub> = 15pF		6.2	10.3	1.0	12.0	ns
			$C_L = 50pF$		7.7	12.3	1.0	14.0	
t <sub>PLH</sub> , t <sub>PHL</sub>	Propagation Delay	3.3 ± 0.3	C <sub>L</sub> = 15pF		7.5	12.3	1.0	14.5	ns
	Time (CET-TC)		$C_L = 50pF$		10.5	15.8	1.0	18.0	
		5.0 ± 0.5	$C_L = 15pF$		4.9	8.1	1.0	9.5	ns
			$C_L = 50pF$		6.4	10.1	1.0	11.5	
t <sub>PHL</sub>	Propagation Delay	3.3 ± 0.3	$C_L = 15pF$		8.9	13.6	1.0	16.0	ns
	Time (MR –Q <sub>n</sub> )		$C_L = 50pF$		11.2	17.1	1.0	19.5	
		5.0 ± 0.5	$C_L = 15pF$		5.5	9.0	1.0	10.5	ns
			$C_L = 50pF$		7.0	11.0	1.0	12.5	
t <sub>PHL</sub>	Propagation Delay	3.3 ± 0.3	$C_L = 15pF$		8.4	13.2	1.0	15.5	ns
	Time (MR –TC)		$C_L = 50pF$		10.9	16.7	1.0	19.0	
		5.0 ± 0.5	$C_L = 15pF$		5.0	8.6	1.0	10.0	ns
			$C_L = 50pF$		6.5	10.6	1.0	12.0	
f <sub>MAX</sub>	Maximum Clock	3.3 ± 0.3	$C_L = 15pF$	80	130		70		MHz
	Frequency		$C_L = 50pF$	55	85		50		
		5.0 ± 0.5	$C_L = 15pF$	135	185		115		MHz
			$C_L = 50pF$	95	125		85		
C <sub>IN</sub>	Input Capacitance		V <sub>CC</sub> = Open		4	10		10	pF
C <sub>PD</sub>	Power Dissipation Capacitance		(3)		23				pF

#### Note

3. C<sub>PD</sub> is defined as the value of the internal equivalent capacitance which is calculated from the operating current consumption without load. Average operating current can be obtained by the equation:

$$I_{CC} (opr) = C_{PD} \bullet V_{CC} \bullet f_{IN} + I_{CC}$$

When the outputs drive a capacitive load, total current consumption is the sum of  $C_{PD}$ , and  $\Delta I_{CC}$  which is obtained from the following formula:

$$\Delta I_{CC} = F_{CP} \bullet V_{CC} \left( \frac{C_{QO}}{2} + \frac{C_{Q1}}{4} + \frac{C_{Q2}}{8} + \frac{C_{Q3}}{16} + \frac{C_{TC}}{16} \right)$$

 $C_{Q0}-C_{Q3}$  and  $C_{TC}$  are the capacitances at Q0–Q3 and TC, respectively.  $F_{CP}$  is the input frequency of the CP.

# **AC Operating Requirements**

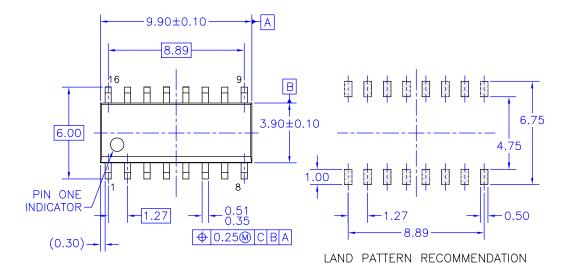
			T <sub>A</sub> =	= 25°C	T <sub>A</sub> = -40°C to +85°C	
Symbol	Parameter	$V_{CC}(V)^{(4)}$	Тур.	Guarant	eed Minimum	Units
t <sub>S</sub>	Minimum Setup Time (P <sub>n</sub> –CP)	3.3		5.5	6.5	ns
		5.0		4.5	4.5	
t <sub>S</sub>	Minimum Setup Time (PE -CP)	3.3		8.0	9.5	ns
		5.0		5.0	6.0	
t <sub>S</sub>	Minimum Setup Time (CEP or CET-CP)	3.3		7.5	9.0	ns
		5.0		5.0	6.0	
t <sub>H</sub>	Minimum Hold Time (P <sub>n</sub> –CP)	3.3		1.0	1.0	ns
		5.0		1.0	1.0	
t <sub>H</sub>	Minimum Hold Time (PE -CP)	3.3		1.0	1.0	ns
		5.0		1.0	1.0	
t <sub>H</sub>	Minimum Hold Time (CEP or CET-CP)	3.3		1.0	1.0	ns
		5.0		1.0	1.0	
$t_W(L), t_W(H)$	Minimum Pulse Width CP (Count)	3.3		5.0	5.0	ns
		5.0		5.0	5.0	
t <sub>W</sub> (L)	Minimum Pulse Width (MR)	3.3		5.0	5.0	ns
		5.0		5.0	5.0	
t <sub>REC</sub>	Minimum Removal Time	3.3		2.5	2.5	ns
		5.0		1.5	1.5	

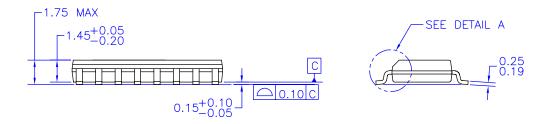
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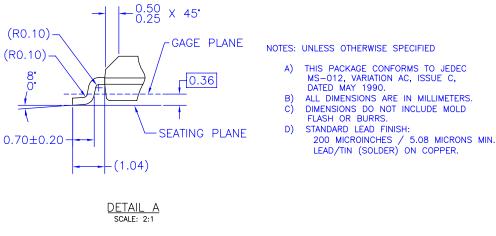
4.  $V_{CC}$  is 3.3 ± 0.3V or 5.0 ± 0.5V.

# **Physical Dimensions**

Dimensions are in millimeters unless otherwise noted.





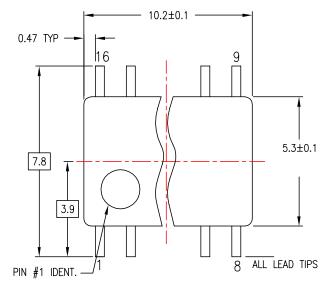


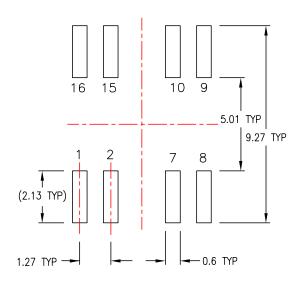
M16AREVK

Figure 3. 16-Lead Small Outline Integrated Circuit (SOIC), JEDEC MS-012, 0.150" Narrow Package Number M16A

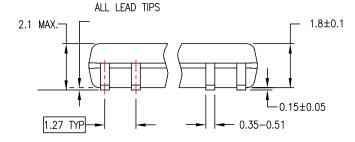
# Physical Dimensions (Continued)

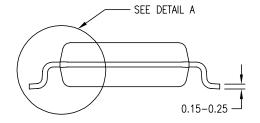
Dimensions are in millimeters unless otherwise noted.





#### LAND PATTERN RECOMMENDATION

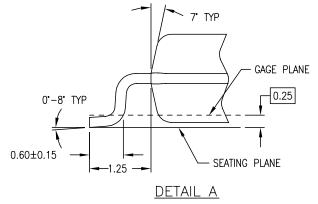




#### DIMENSIONS ARE IN MILLIMETERS

#### NOTES:

- A. CONFORMS TO EIAJ EDR-7320 REGISTRATION, ESTABLISHED IN DECEMBER, 1998.
  B. DIMENSIONS ARE IN MILLIMETERS.
  C. DIMENSIONS ARE EXCLUSIVE OF BURRS, MOLD FLASH, AND TIE BAR EXTRUSIONS.

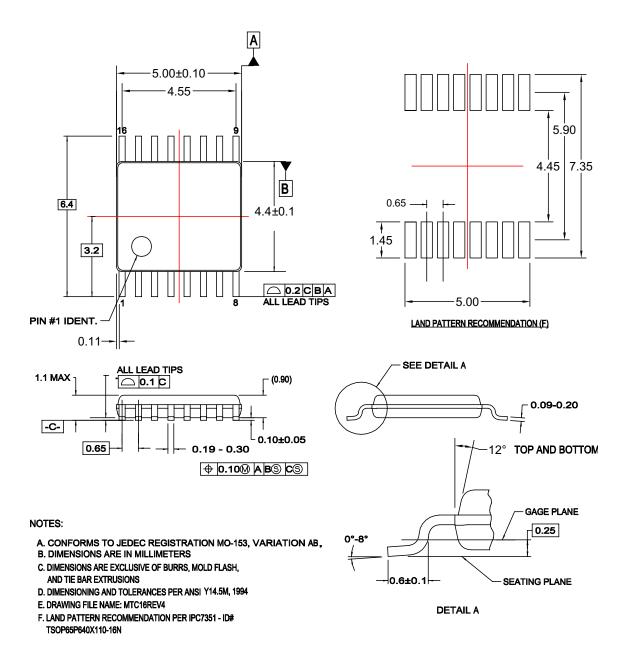


M16DREVC

Figure 4. 16-Lead Small Outline Package (SOP), EIAJ TYPE II, 5.3mm Wide Package Number M16D

# Physical Dimensions (Continued)

Dimensions are in millimeters unless otherwise noted.



MTC16rev4

Figure 5. 16-Lead Thin Shrink Small Outline Package (TSSOP), JEDEC MO-153, 4.4mm Wide Package Number MTC16





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